

# Copyright statement

- The images and the pictures in this lecture are provided by the CDs accompanied by the books
  1. University Physics, Bauer and Westfall, McGraw-Hill, 2011.
  2. Principles of Physics, Halliday, Resnick, and Walker, Wiley, 8<sup>th</sup> and 9<sup>th</sup> Ed.
- The rest is made by me.

# Ch. 8 Systems of particles and extended objects



# Center of mass

조금 더 복잡한 물체의 운동

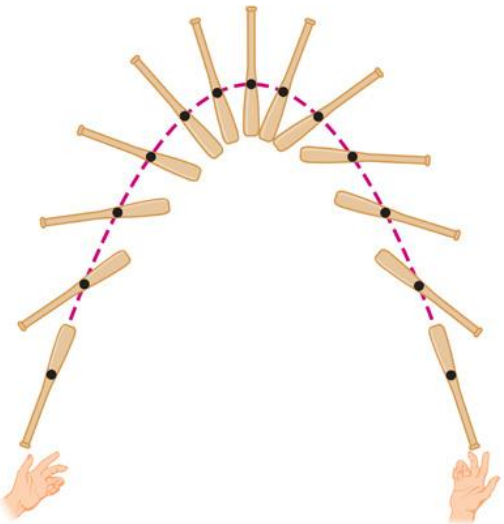
- (1) 물체의 크기를 무시할 수 없거나
- (2) 여러 입자들로 이루어진 물리계



(a)

가장 간단하게 기술할 수 있는 운동  
(질량중심의 운동)

조금 더 복잡한 운동  
(질량중심에 대해 움직이는 상대운동 및 회전)



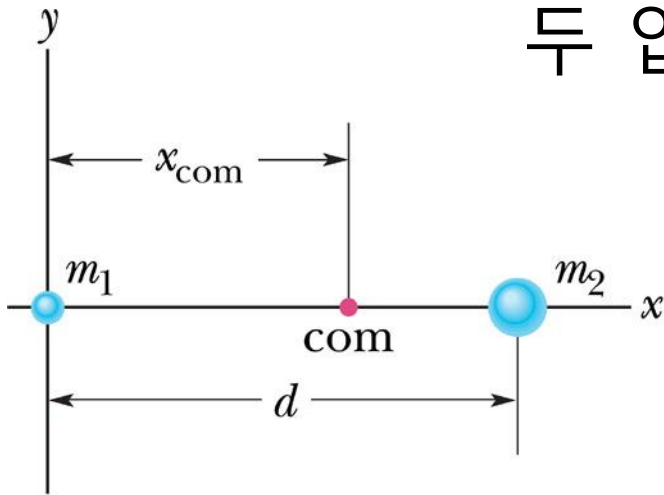
(b)

## center of mass

- (1) 모든 질량이 그 점에 모여 있고
- (2) 외부 힘이 모두 그 점에 작용하는 것처럼 움직이는 점.

# 두 입자로 이루어진 물리계의 질량중심

한 물체를 원점에 두었을 때

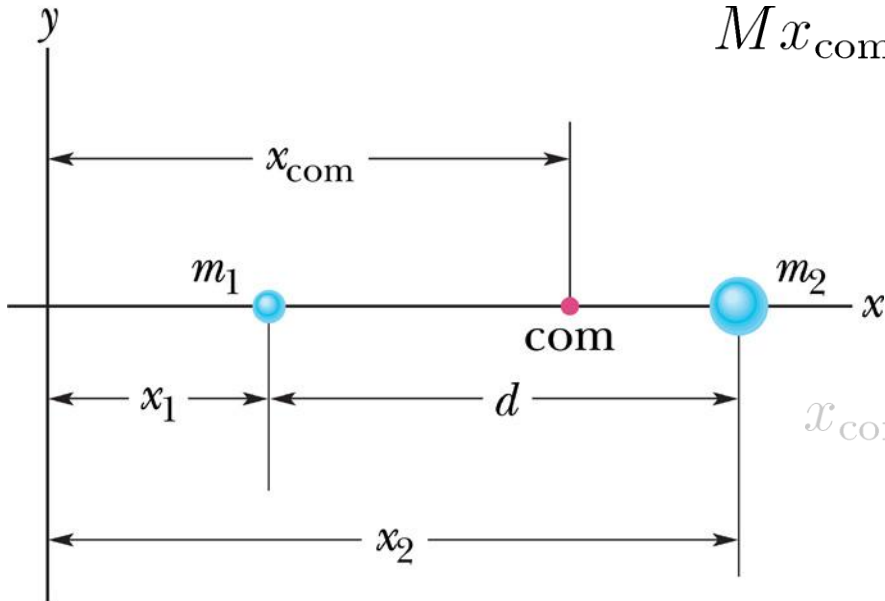


(a)

$$x_{\text{com}} = \frac{m_2}{m_1 + m_2} d$$

임의의 점이 원점일 때

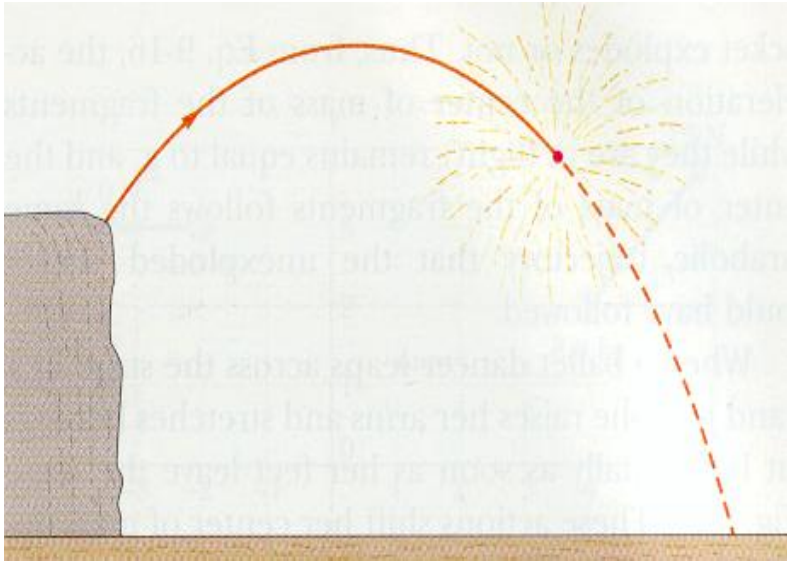
$$M x_{\text{com}} = m_1 x_1 + m_2 x_2, \quad M = m_1 + m_2$$



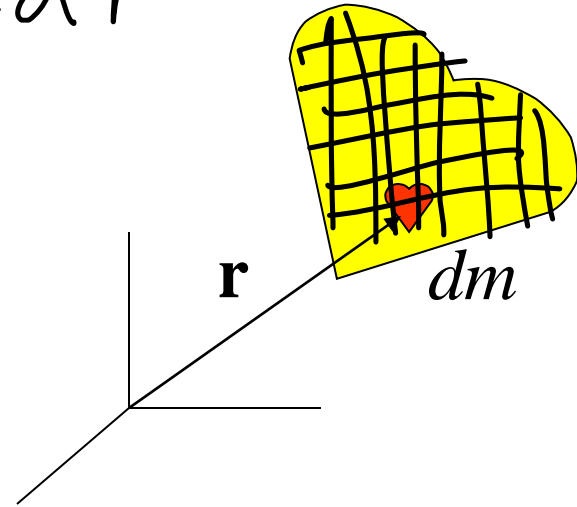
(b)

$$x_{\text{com}} = \frac{m_1 x_1 + m_2 x_2}{m_1 + m_2}$$

$$\begin{aligned} x_{\text{com}} &= \frac{m_1 x_1 + m_2 x_2 + \cdots + m_n x_n}{M} \\ &= \frac{1}{M} \sum_{i=1}^n m_i x_i \end{aligned}$$



$$dV = d^3r$$



$$M \mathbf{r}_{\text{com}} = \sum m_i \mathbf{r}_i$$

$$x_{\text{com}} = \frac{1}{M} \sum_{i=1}^n m_i x_i,$$

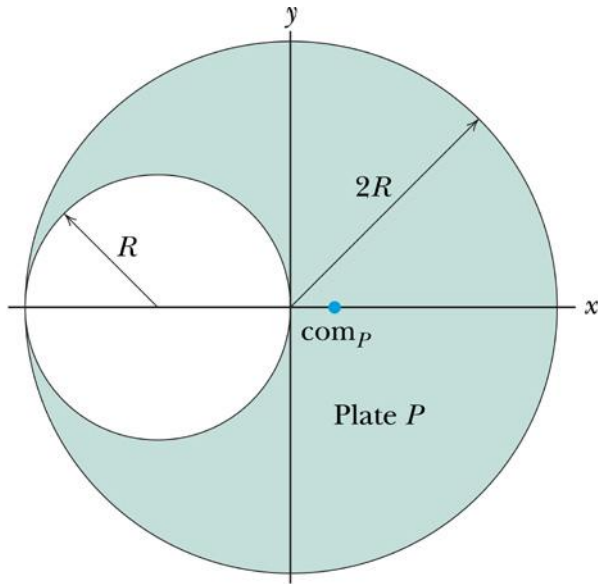
$$y_{\text{com}} = \frac{1}{M} \sum_{i=1}^n m_i y_i,$$

$$z_{\text{com}} = \frac{1}{M} \sum_{i=1}^n m_i z_i.$$

밀도가 일정한 경우:  $\rho = \frac{dm}{dV} = \frac{M}{V}$

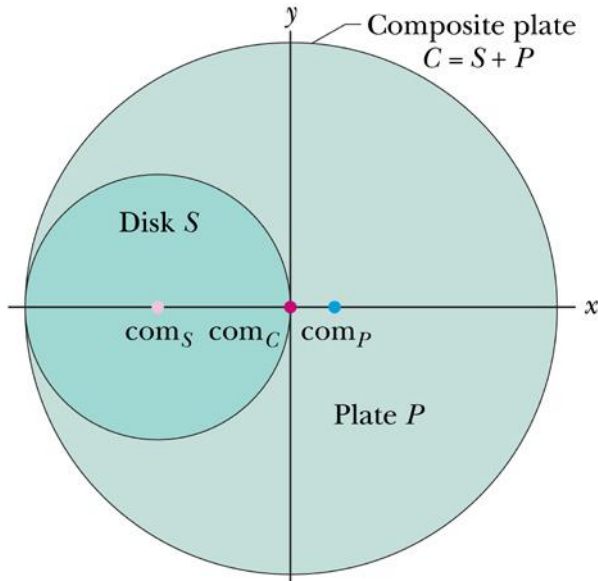
$$\begin{aligned} \mathbf{r}_{\text{cm}} &= \frac{1}{M} \int \mathbf{r} dm \quad \rho(\vec{r}) \\ &= \frac{1}{M} \int \mathbf{r} \left( \frac{M}{V} \right) d^3\mathbf{r} = \frac{1}{V} \int \mathbf{r} d^3\mathbf{r} \end{aligned}$$

# Sample problem



(a)

$$x_{S+P} = \frac{m_S x_S + m_P x_P}{m_S + m_P} = 0$$



(b)

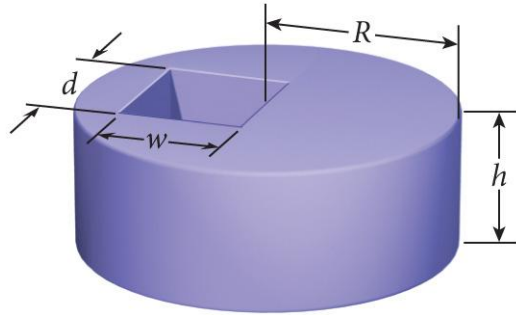
$$x_P = -x_S \frac{m_S}{m_P} = -x_S \frac{1}{3} = \frac{1}{3}R$$



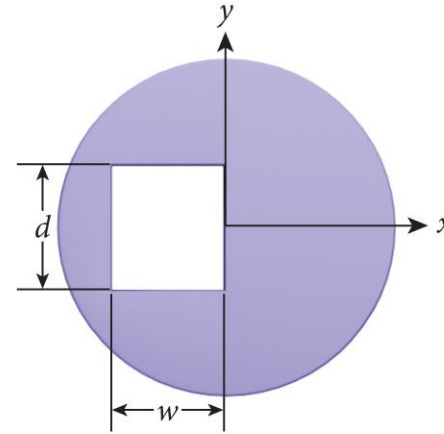
(c)

# S.P. 8.5 Cm of a disk with a hole

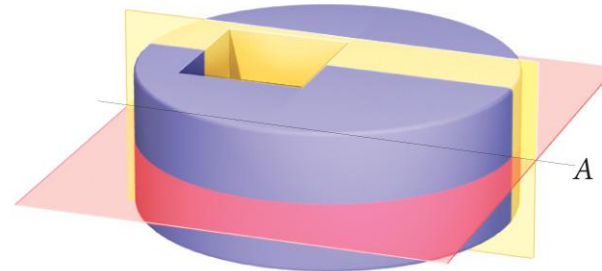
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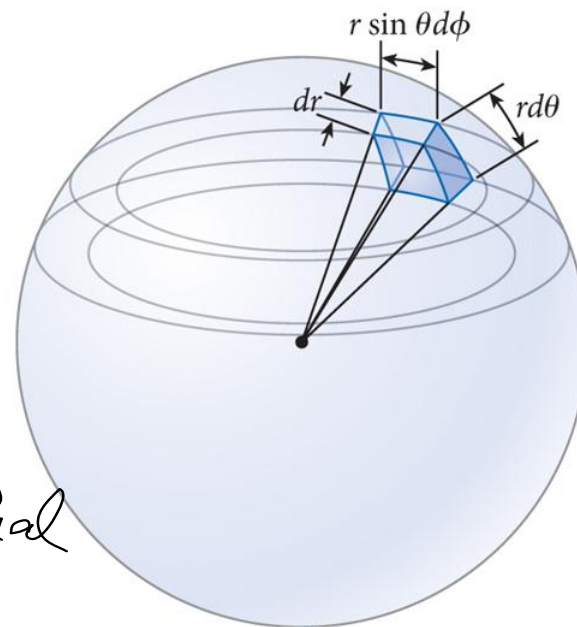
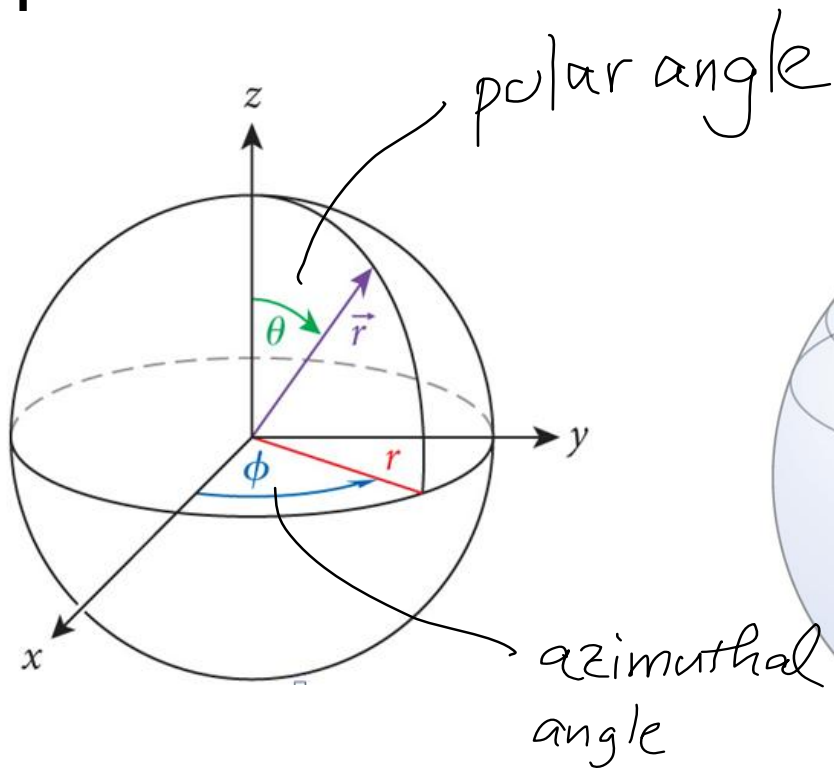


(a)



(b)

# Spherical coordinates



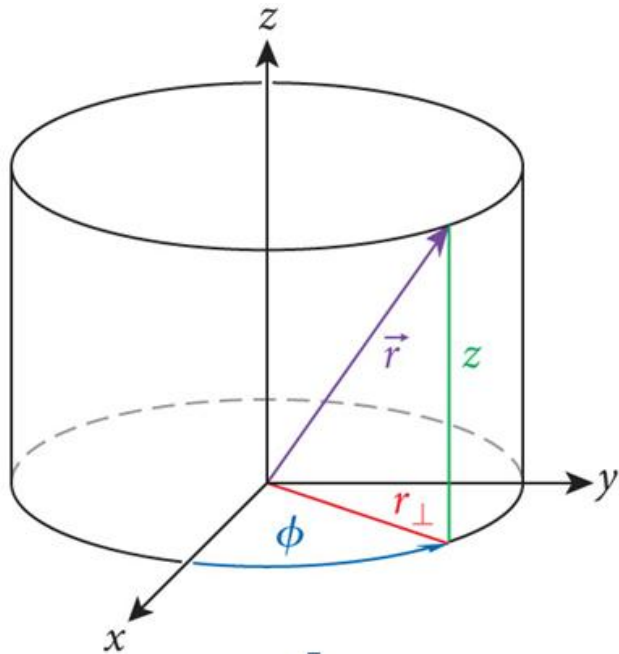
$$\begin{aligned}x &= r \sin \theta \cos \phi, \\y &= r \sin \theta \sin \phi, \\z &= r \cos \theta.\end{aligned}$$

Volume element

$$dV = r^2 dr \sin \theta d\theta d\phi$$



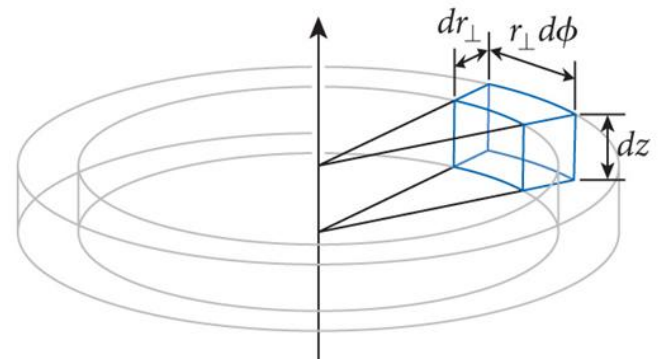
# Cylindrical coordinates



$$x = r_{\perp} \cos \phi,$$

$$y = r_{\perp} \sin \phi,$$

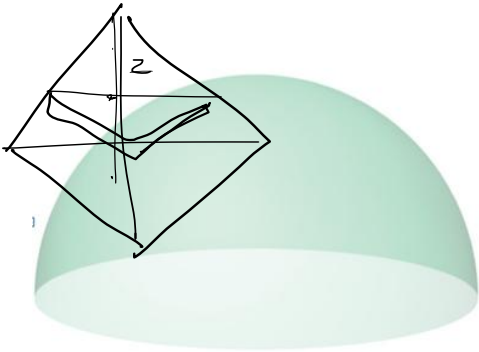
$$z = z.$$



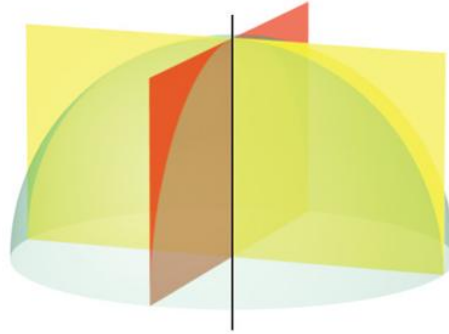
Volume element

$$dV = r_{\perp} dr_{\perp} d\phi dz$$

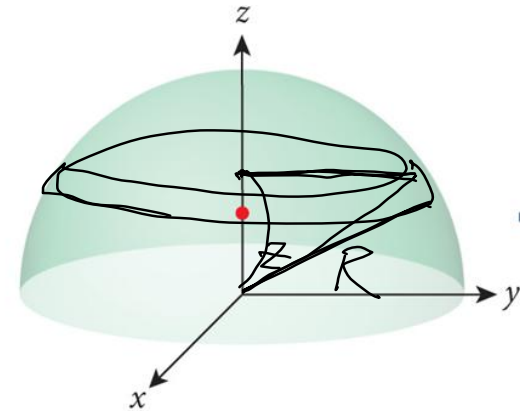
# Ex. 8.5: CM for a half-sphere



(a)



(b)



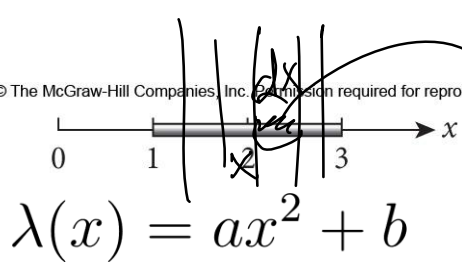
(c)

$$\begin{aligned}
 z_{CM} &= \frac{1}{M} \int z dm \\
 &= \frac{1}{V} \int_0^R z \pi (R^2 - z^2) dz = \frac{\pi}{V} \int_0^R (zR^2 - z^3) dz \\
 &= \frac{\pi}{V} \left( \frac{R^4}{4} \right) = \frac{\pi R^4}{4 \left( \frac{3}{8} \pi R^3 \right)} = \frac{3}{8} R
 \end{aligned}$$

$$z_{CM} = \frac{3}{8} R$$

# SP 8.3: CM of a long, thin rod

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$$dm = \lambda(x) dx$$

$$x_{\text{com}} = \frac{1}{M} \int x dm$$

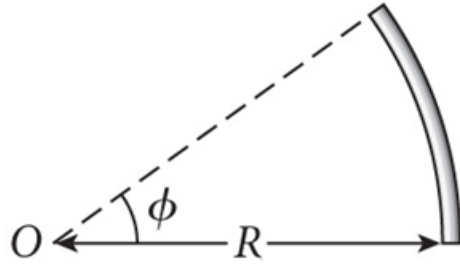
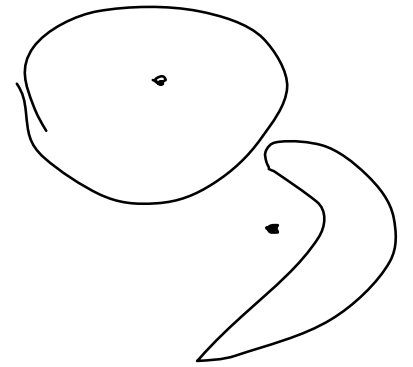
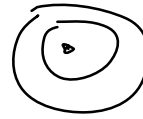
$$= \frac{1}{M} \int_1^3 x \lambda(x) dx$$

$$= \frac{1}{M} \int_1^3 (ax^3 + bx) dx$$

$$= \frac{1}{M} (20a + 4b) = \frac{20a + 4b}{\frac{26}{3}a + 2b}$$

$$M = \int dm = \int \lambda(x) dx = \int_1^3 (ax^2 + b) dx = \frac{26}{3}a + 2b$$

# Prob. 8.21



Center of mass?

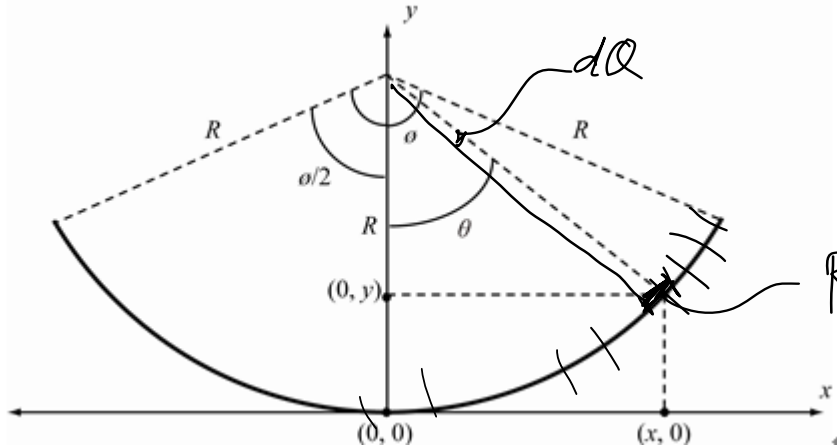
$$y_{\text{com}} = \frac{1}{M} \int_0^{\phi} \lambda R d\theta R (1 - \cos\theta)$$

$$= \frac{2\lambda R^2}{M} \int_0^{\phi} (1 - \cos\theta) d\theta$$

$$= \frac{2\lambda R^2}{M} \left( \frac{\phi}{2} - \sin \frac{\phi}{2} \right)$$

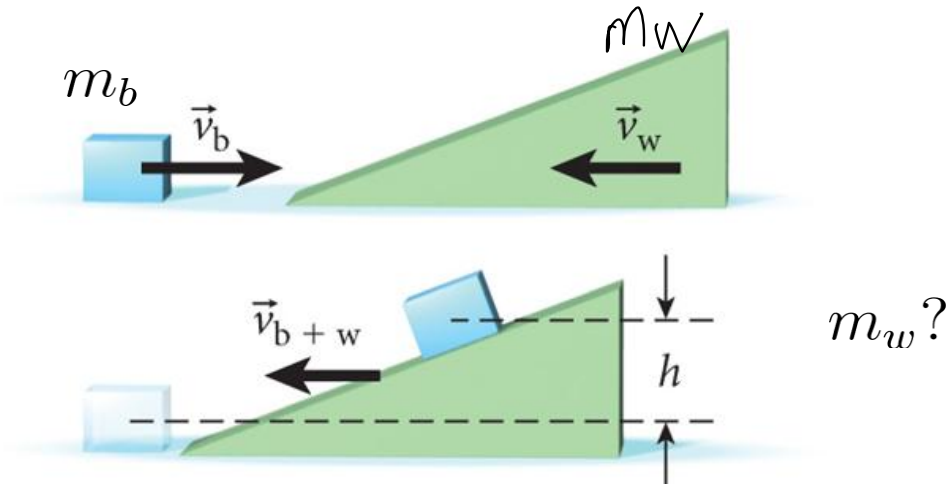
$$\lambda R \phi = M$$

$$y_{\text{com}} = \frac{2R}{\phi} \left( \frac{\phi}{2} - \sin \frac{\phi}{2} \right) = R \left( 1 - \frac{\sin \frac{\phi}{2}}{\frac{\phi}{2}} \right)$$



$$y_{\text{CM}} = R - \frac{R \sin(\phi/2)}{\phi/2}$$

# Prob. 8.36



$$m_b v_b + m_w v_w = (m_b + m_w) v_{b+w}$$

$$\frac{1}{2} m_b v_b^2 + \frac{1}{2} m_w v_w^2 = \frac{1}{2} (m_b + m_w) v_{b+w}^2 + m_b g h$$

# 입자계에 대한 Newton의 법칙

$$\mathbf{F}_{\text{net}} = M\mathbf{a}_{\text{com}}$$

$$F_{\text{net},x} = Ma_{\text{com},x}, \quad F_{\text{net},y} = Ma_{\text{com},y}, \quad F_{\text{net},z} = Ma_{\text{com},z}.$$

증명:

$$M\mathbf{r}_{\text{com}} = m_1\mathbf{r}_1 + m_2\mathbf{r}_2 + \cdots + m_n\mathbf{r}_n$$

$$M\mathbf{v}_{\text{com}} = m_1\mathbf{v}_1 + m_2\mathbf{v}_2 + \cdots + m_n\mathbf{v}_n$$

$$\begin{aligned} M\mathbf{a}_{\text{com}} &= m_1\mathbf{a}_1 + m_2\mathbf{a}_2 + \cdots + m_n\mathbf{a}_n \\ &= \mathbf{F}_1 + \mathbf{F}_2 + \cdots + \mathbf{F}_n = \mathbf{F}_{\text{net}} \end{aligned}$$

선운동량의 정의:

$$\mathbf{p} \equiv m\mathbf{v}$$

따라서 뉴턴의 방정식은

$$\mathbf{F}_{\text{net}} = \frac{d\mathbf{p}}{dt}$$

가 된다.

$$\mathbf{F}_{\text{net}} = \frac{d\mathbf{p}}{dt} = \frac{d}{dt}(m\mathbf{v}) = m\frac{d\mathbf{v}}{dt} = m\mathbf{a}$$

# 입자계의 linear momentum

여러 입자들이 있는 경우 선운동량은

$$\begin{aligned}\mathbf{P} &= \mathbf{p}_1 + \mathbf{p}_2 + \cdots + \mathbf{p}_n \\ &= m_1\mathbf{v}_1 + m_2\mathbf{v}_2 + \cdots + m_n\mathbf{v}_n = M\mathbf{v}_{\text{com}}\end{aligned}$$

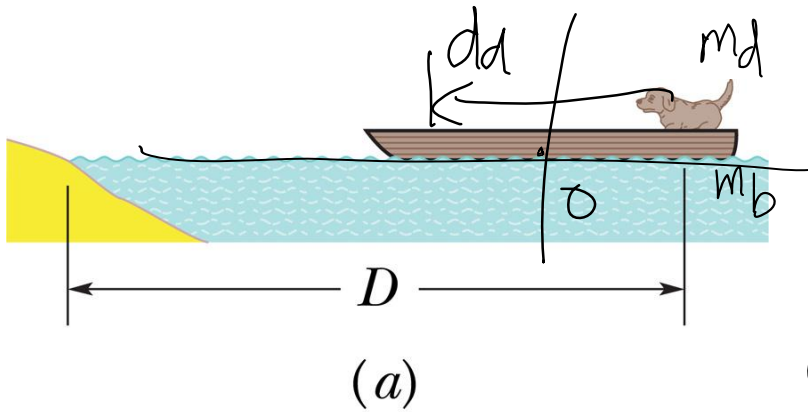
이 됨을 알 수 있다. 따라서 위 식을 시간에 대해 미분하면

$$\frac{d\mathbf{P}}{dt} = M\frac{d\mathbf{v}_{\text{com}}}{dt} = M\mathbf{a}_{\text{com}}$$

을 얻는다.



# Problem : 개와 배



$$m_d d_d + m_b d_b = 0$$

$$|d_b| = -\frac{m_d}{m_b} |d_d|$$

$$|d_d| - |d_b| = \frac{m_b - m_d}{m_b} |d_d|$$

Dog's displacement  $\vec{d}_d$



Boat's displacement  $\vec{d}_b$

(b)

$$D - \frac{m_b - m_d}{m_b} |d_d|$$