

Copyright statement

- The images and the pictures in this lecture are provided by the CDs accompanied by the books
 1. University Physics, Bauer and Westfall, McGraw-Hill, 2011.
 2. Principles of Physics, Halliday, Resnick, and Walker, Wiley, 8th and 9th Ed.
- The rest is made by me.

Displacement at time t

$$x(t) = x_m \cos(\omega t + \phi)$$

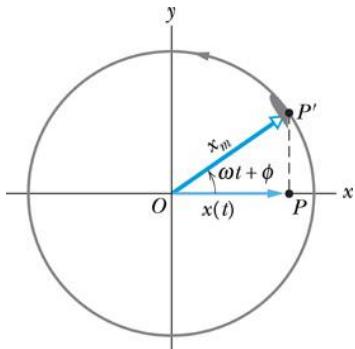
Diagram illustrating the components of the displacement equation:

- Amplitude: x_m
- Angular frequency: ω
- Time: t
- Phase constant or phase angle: ϕ
- Phase: $\omega t + \phi$

Mathematical derivation:

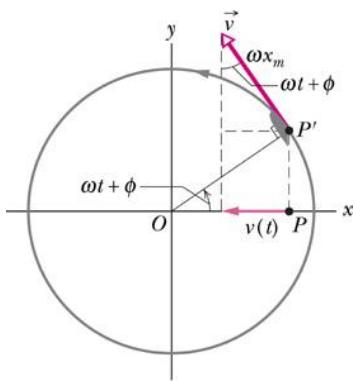
$$x_m \cos \omega t = x_m \cos \omega(t + T)$$
$$\omega(t + T) = \omega t + 2\pi$$
$$\omega T = 2\pi$$
$$\omega = \frac{2\pi}{T} = 2\pi f$$

SHO and uniform CM



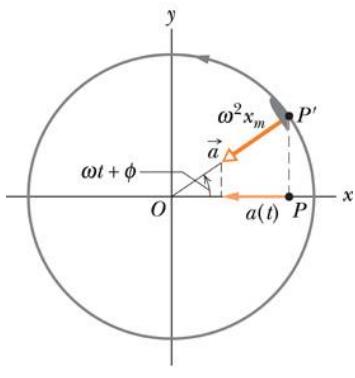
(a)

$$x(t) = x_m \cos(\omega t + \phi)$$



(b)

$$v(t) = -\omega x_m \sin(\omega t + \phi)$$

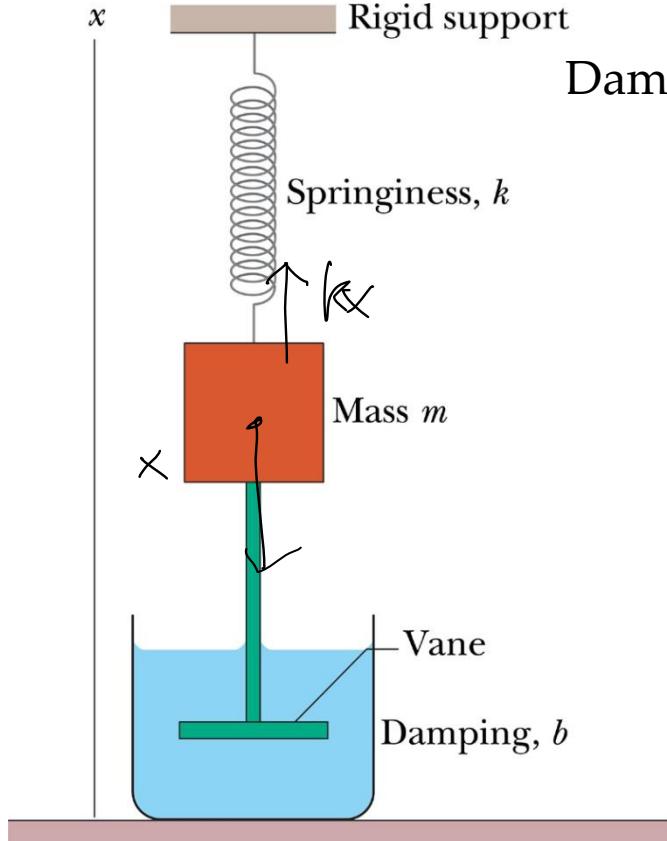


(c)

$$a(t) = -\omega^2 x_m \cos(\omega t + \phi)$$



Damped simple harmonic motion



Damping force가 $F_d = -bv$ 라고 가정하면

$$-bv - kx = ma$$

$$m \frac{d^2x}{dt^2} + b \frac{dx}{dt} + kx = 0$$

$$-ma^2 + iba + k = 0$$

$$x = Ae^{iat}$$

$$ma^2 - iba - k = 0$$

$$kx - mg = ma$$

$$x = \frac{mg}{k}$$

$$a = \frac{1}{2m} (ib \pm \sqrt{4mk - b^2})$$

$$k(x - mg) = ma$$

$$= i\frac{b}{2m} \pm \sqrt{\frac{k}{m} - \frac{b^2}{4m^2}}$$

$$x' = x - mg$$

$$kx' = ma$$



간단한 미분 방정식 풀기

$$\frac{dx^2}{dt^2} + \omega^2 x = 0$$

$$m \frac{d^2x}{dt^2} + m\omega^2 x = 0$$

$$x(t) = x_m \cos \omega t, \quad x_m \sin \omega t$$

$$x(t) = x_m \cos(\omega t + \phi)$$

$$x = A e^{iat} \rightarrow a^2 = \omega^2 \rightarrow a = \pm \omega$$

$$e^{iat}$$

$$\cos \omega t = \frac{1}{2} (e^{i\omega t} + e^{-i\omega t})$$

$$\sin \omega t = \frac{1}{2i} (e^{i\omega t} - e^{-i\omega t})$$

$$x(t) = A e^{i\omega t} + B e^{-i\omega t}$$

$$* e^{i\omega t} = \cos \omega t + i \sin \omega t$$

$$x(t) = (A + B) \cos \omega t + i(A - B) \sin \omega t$$

Small damping

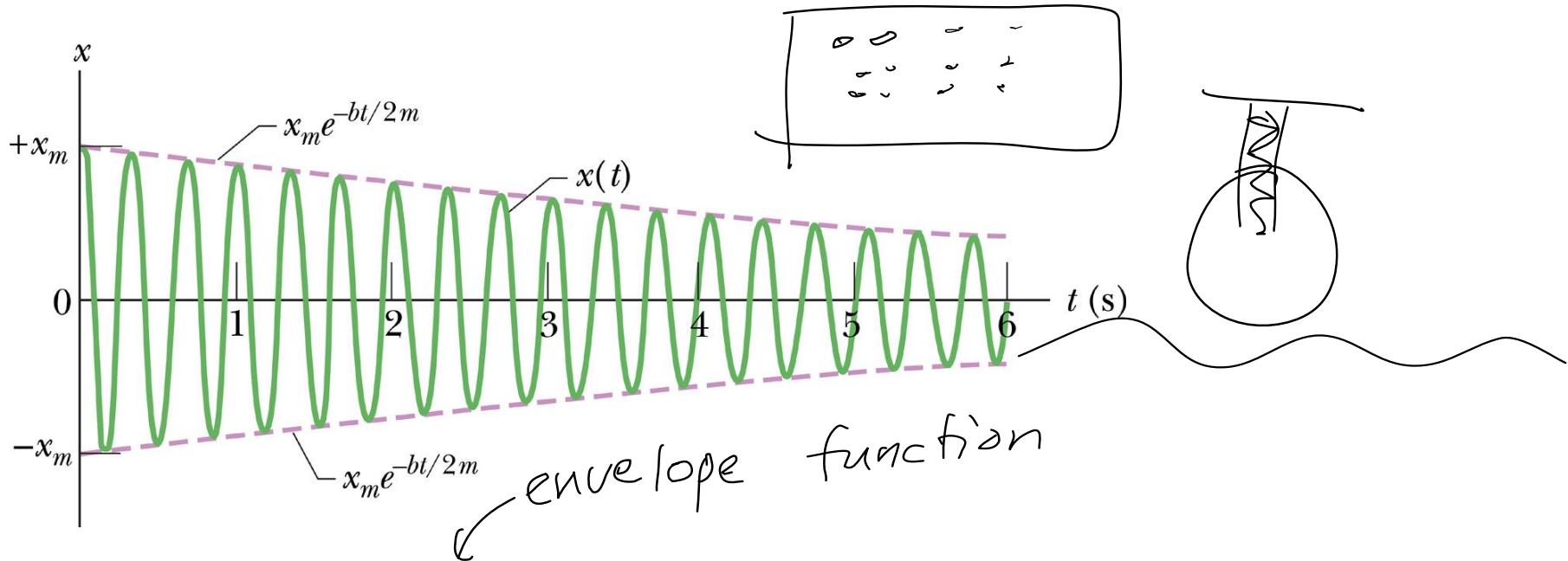
$$F_d = -bv = -b \frac{dx}{dt}$$

$$m \frac{d^2x}{dt^2} = -b \frac{dx}{dt} - kx \longrightarrow \frac{d^2x}{dt^2} + \frac{b}{m} \frac{dx}{dt} + \frac{k}{m}x = 0$$

$$x = Ae^{at} \rightarrow a^2 + \frac{b}{m}a + \frac{k}{m}a = 0$$

$$a = -\frac{b}{2m} \pm \sqrt{\left(\frac{b}{2m}\right)^2 - \frac{k}{m}} = -\frac{b}{2m} \pm i\sqrt{\frac{k}{m} - \left(\frac{b}{2m}\right)^2}$$

$$x(t) = Ae^{-bt/2m} \cos(\omega't + \phi)$$



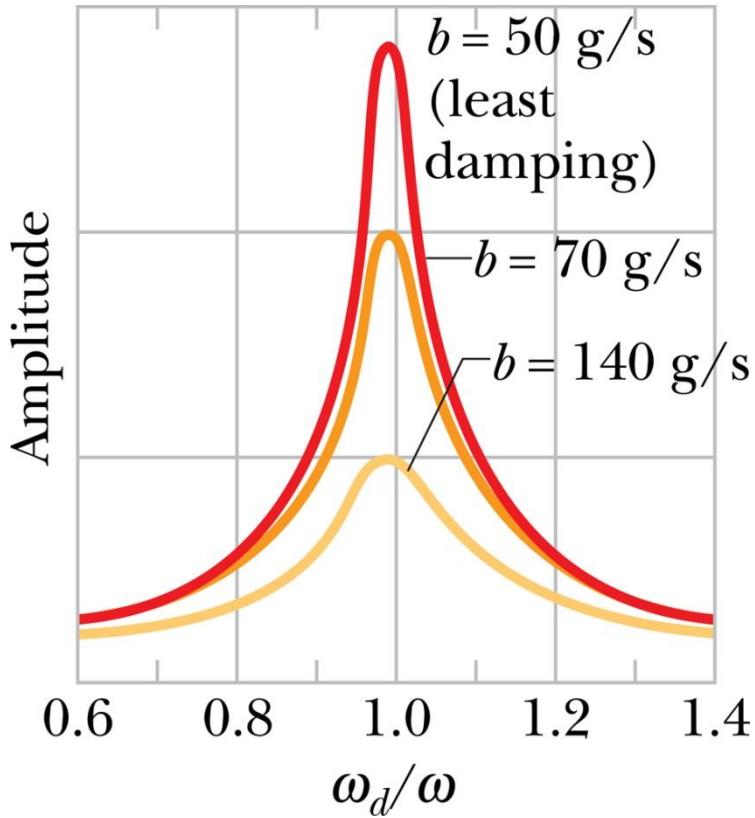
$$x(t) = x_m e^{-bt/2m} \cos(\omega' t + \phi) \quad \omega' = \sqrt{\frac{k}{m} - \frac{b^2}{4m^2}}$$

$k/m - b^2/4m^2 > 0$ underdamping

$k/m - b^2/4m^2 = 0$ critical damping

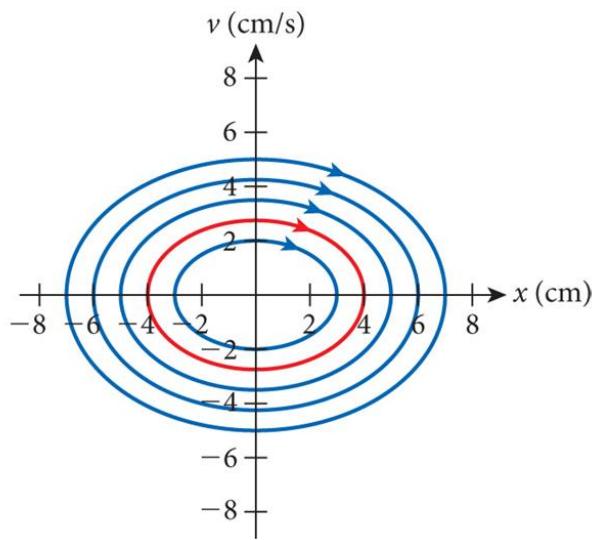
$k/m - b^2/4m^2 \ll 0$ overdamping

Forced oscillations and resonance



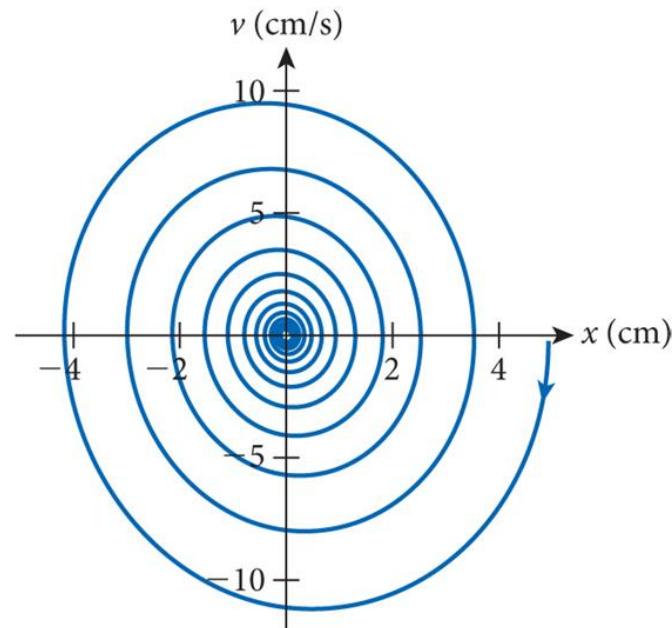
$$x(t) = x_m \cos(\omega_d t + \phi)$$

Phase space



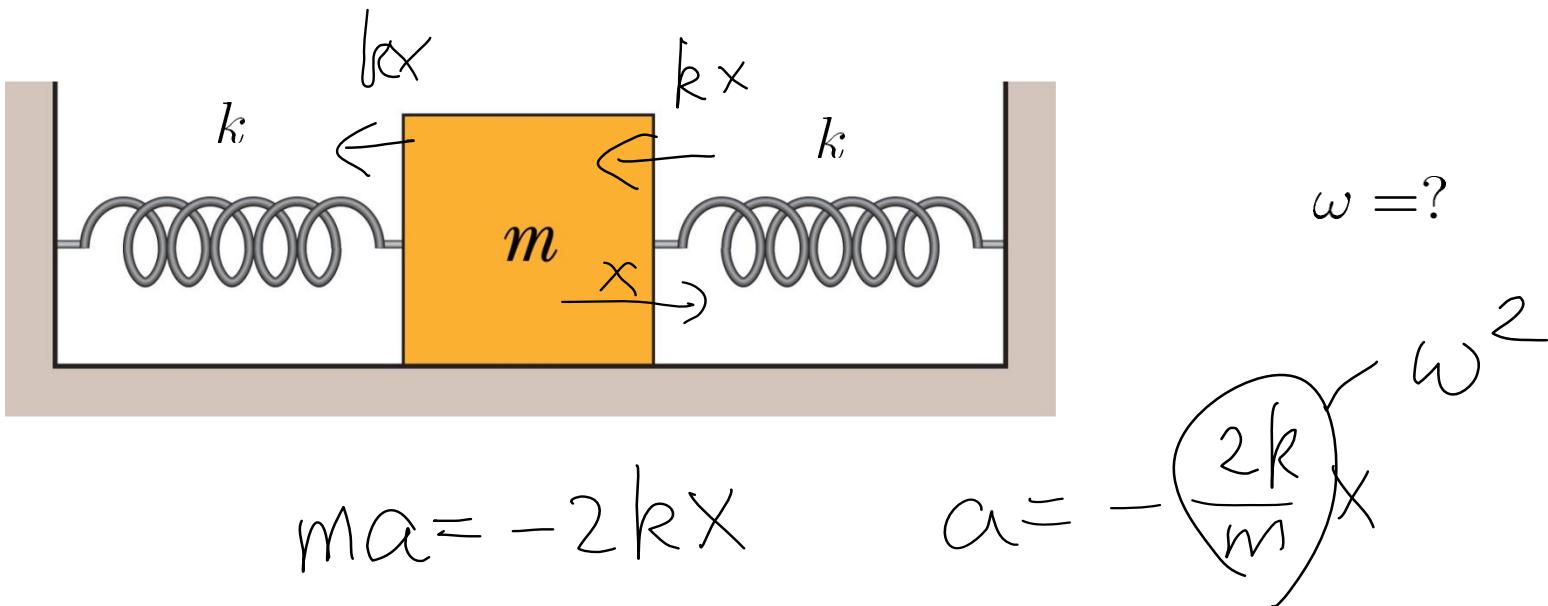
Simple harmonic oscillator

$$E = \frac{1}{2}mv^2 + \frac{1}{2}kx^2$$



Damped oscillator

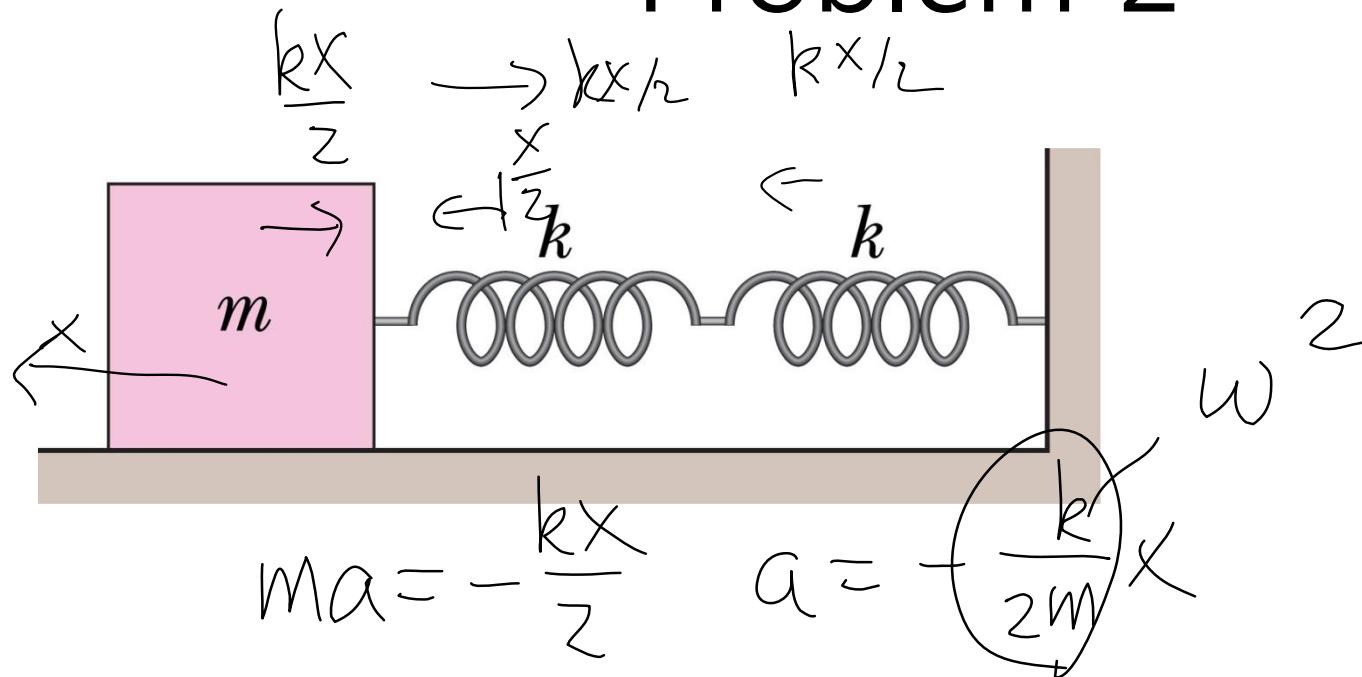
Problem 1



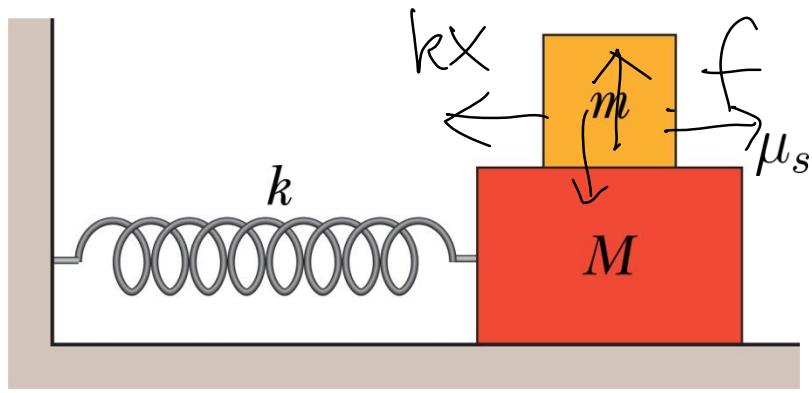
$$ma = -2kx \quad a = -\left(\frac{2k}{m}\right)x$$

$$\omega = \sqrt{\frac{2k}{m}}$$

Problem 2



Problem 3



$$kx = (M+m) \alpha$$

$$\omega^2 = \frac{k}{M+m}$$

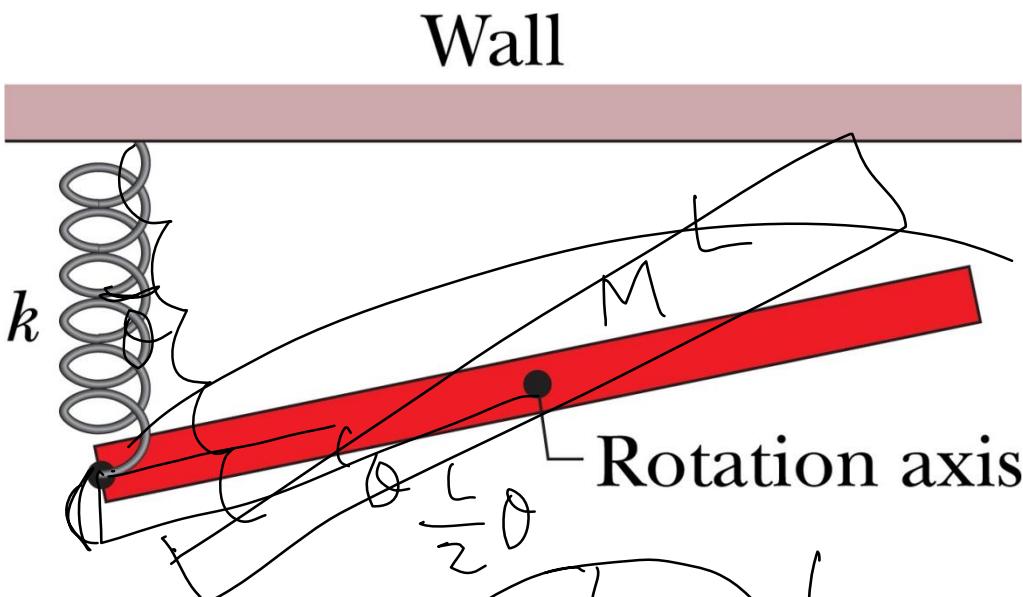
$$kx_{\max} = \mu_s M g$$

$$x_{\max} = \frac{\mu_s M g}{k}$$

$$F = -kx$$

Problem 4

$$a = -\omega^2 x$$



$$\tau = -k \frac{L}{2} \dot{\theta} = -k \frac{L^2}{4} \ddot{\theta} = I \ddot{\theta}$$

$$= \frac{ML^2}{12} \ddot{\theta} \quad // \omega^2$$

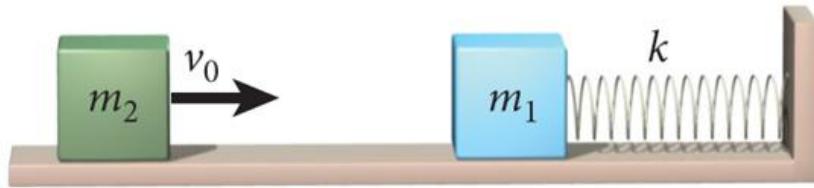
$$I =$$

$$\ddot{\theta} = -k \frac{3}{4} \frac{\dot{\theta}}{ML^2} = \left(\frac{3k}{M} \right) \dot{\theta}$$

$$\begin{aligned} \tau &= -k\theta \\ &= I\ddot{\theta} \\ \ddot{\theta} &= -\frac{k}{I}\theta \end{aligned}$$

$\omega = \sqrt{\frac{3k}{M}}$

Problem 5



Max. compression and
the time to get there

$$m_2 v_0 = (m_1 + m_2) V$$

$$V = \frac{m_2}{m_1 + m_2} v_0$$

~~$$(m_1 + m_2) V^2 = k X_{\max}^2$$~~

$$-kx = (m_1 + m_2) a$$

$$T = 2\pi \sqrt{\frac{m_1 + m_2}{k}}$$

$$\begin{aligned} X_{\max}^2 &= \frac{1}{k} (m_1 + m_2) \frac{m_2^2 v_0^2}{(m_1 + m_2)^2} \\ &= \frac{m_2^2 v_0^2}{k(m_1 + m_2)} \end{aligned}$$

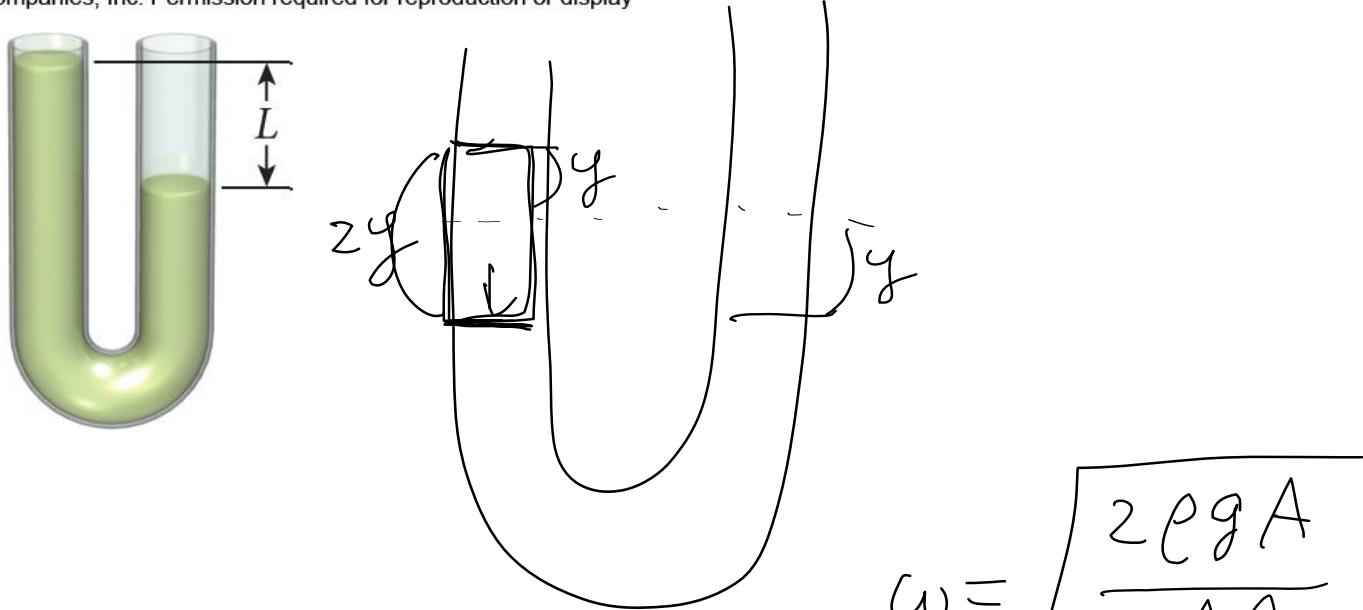
$$X_{\max} = \sqrt{\frac{m_2 v_0}{k(m_1 + m_2)}}$$

$$\omega = \sqrt{\frac{k}{m_1 + m_2}}$$

$$t = \frac{T}{4} = \frac{\pi}{2} \sqrt{\frac{m_1 + m_2}{k}}$$

Problem 6

Copyright © The McGraw-Hill Companies, Inc. Permission required for reproduction or display



$$\rho A g \cdot 2y = M a$$

$$a = \frac{2\rho g y}{M} A = \omega^2$$

$$\omega = \sqrt{\frac{2\rho g A}{M}}$$

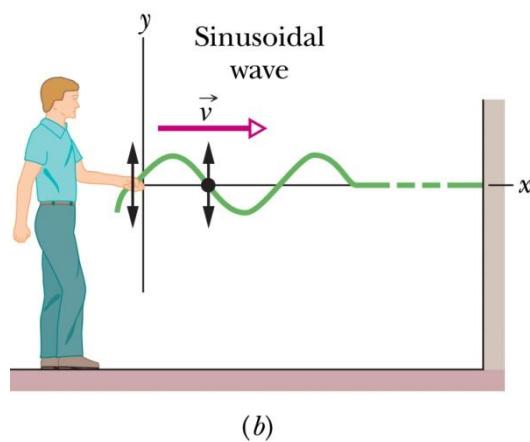
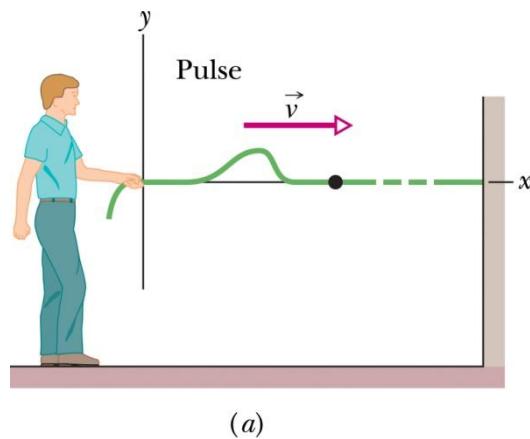
Ch. 15 Waves



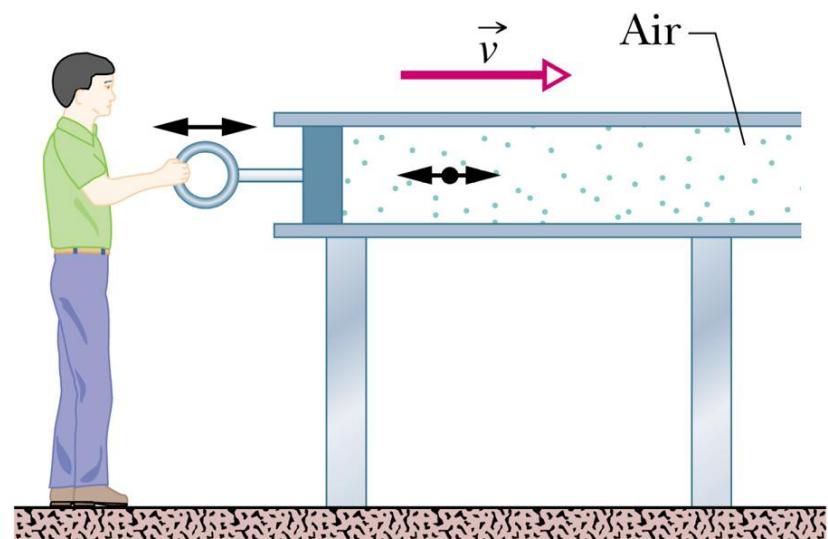
Waves

- 물체(매질)은 제자리에서 진동을 하며 에너지를 전달하는 현상
- 파동의 종류
 - (1) 역학적 파동: 수면파, 음파, 줄의 파동
 - (2) 전자기파: 전기장과 자기장이 진동
 - (3) 물질파: 입자의 양자역학적 현상

Transverse wave



Longitudinal wave



Wavelength and frequency

$$y(x, t) = y_m \sin(kx - \omega t)$$

displacement

amplitude

ang. freq.
angular
wave number
phase

$$\text{Angular wave number } k = \frac{2\pi}{\lambda}$$

$$\text{Angular frequency } \omega = \frac{2\pi}{T}$$

$$k\lambda = 2\pi = \omega T$$

frequency

$$f = \frac{1}{T} = \frac{\omega}{2\pi}$$

