Communication Systems II

[KECE322_01] <2012-2nd Semester>

Lecture #7
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12년 9월 17일 월요일

Outline

- Autocorrelation and Cross-correlation
- Random process in LTI system
- Power spectral density
- Gaussian random processes
- White processes
- White Gaussian noise processes

Autocorrelation and Cross-Correlation Functions

Autocorrelation function for a stationary process is an even function.

$$R_X(t_1, t_2) = E[X(t_1)X(t_2)] = R_X(t_2, t_1)$$

Let $\tau = t_1 - t_2$, we have

$$R_X(\tau) = R_X(-\tau)$$

Cross-correlation function for a stationary process is an odd function.

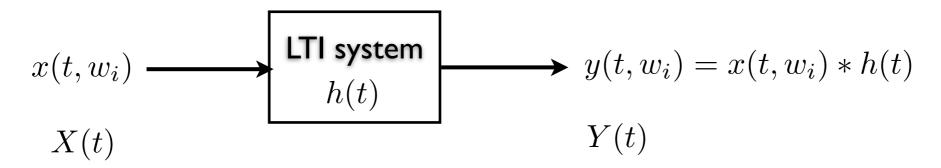
$$R_{XY}(t_1, t_2) = E[X(t_1)Y(t_2)] = R_{YX}(t_2, t_1)$$

Let $\tau = t_1 - t_2$, we have

$$R_{XY}(\tau) = R_{YX}(-\tau)$$

Multiple Random Process

Example in the LTI system



Independent processes

Two random processes X(t) and Y(t) are independent if, for all $t_1,\ t_2$, the random variables $X(t_1)$ and $Y(t_2)$ are independent. Similarly, $X(t_1)$ and $Y(t_2)$ are uncorrelated if $X(t_1)$ and $Y(t_2)$ are uncorrelated for all $t_1,\ t_2$.

Cross-Correlation

$$R_{XY}(t_1, t_2) = E[X(t_1)Y(t_2)]$$

From the definition of cross-correlation, in general, we have

$$R_{XY}(t_1, t_2) = E[X(t_1)Y(t_2)] = R_{YX}(t_2, t_1)$$

- Jointly wide-sense stationary if
 - I) X(t) and Y(t) are individually stationary
 - 2) $R_{XY}(t_1, t_2)$ depends only on $\tau = t_1 t_2$

For jointly stationary process, it follows that

$$R_{XY}(\tau) = R_{YX}(-\tau)$$

Example

X(t), Y(t): Jointly stationary RPs

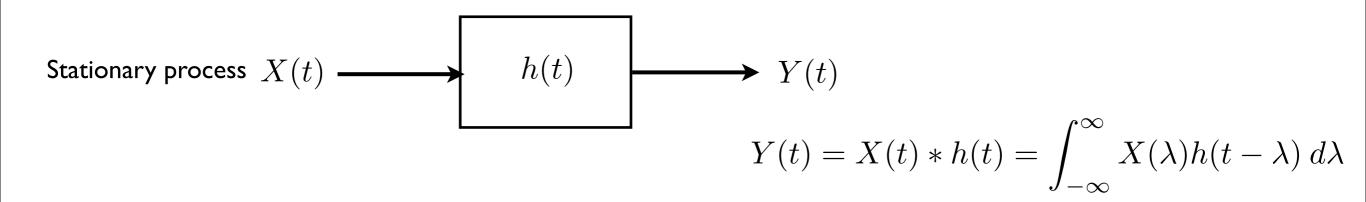
Determine the autocorrelation of the process Z(t) = X(t) + Y(t)

$$R_{Z}(t + \tau, t) = E[Z(t + \tau)Z(t)]$$

$$= E[(X(t + \tau) + Y(t + \tau))(X(t) + Y(t))]$$

$$= R_{X}(\tau) + R_{Y}(\tau) + R_{XY}(\tau) + R_{XY}(-\tau)$$

Random Processes and Linear Systems



If X(t) is stationary process, Y(t) is also stationary!!!

$$E[X(t)] = m_X$$

$$R_X(\tau) = E[X(t+\tau)X(t)]$$

$$E[Y(t)] = m_Y$$

$$R_Y(\tau) = E[Y(t+\tau)Y(t)]$$

• Mean of Y(t)

$$E[Y(t)] = E\left[\int_{-\infty}^{\infty} X(\tau)h(t-\tau) d\tau\right]$$

$$= \int_{-\infty}^{\infty} \left[\int_{-\infty}^{\infty} X(\tau)h(t-\tau) d\tau\right] f_{X(\tau)}(x) dx$$

$$= \int_{-\infty}^{\infty} \left[\int_{-\infty}^{\infty} X(\tau)f_{X(\tau)}(x) dx\right] h(t-\tau) d\tau$$

$$= \int_{-\infty}^{\infty} E[X(\tau)]h(t-\tau) d\tau$$

$$= \int_{-\infty}^{\infty} m_X h(t - \tau) \, d\tau$$

change of variable

$$\lambda = t - u$$

$$= m_X \int_{-\infty}^{\infty} h(\lambda) \, d\lambda \quad \equiv m_Y$$

• Cross-correlation

$$E[X(t_1)Y(t_2)] = E[X(t_1)Y(t_2)] = E\left[X(t_1)\int_{-\infty}^{\infty} X(s)h(t_2 - s) ds\right]$$

$$= \int_{-\infty}^{\infty} E[X(t_1)X(s)]h(t_2 - s) ds$$

$$= \int_{-\infty}^{\infty} R_X(t_1 - s)h(t_2 - s) ds$$

change of variable

$$u = s - t_2$$
 = $\int_{-\infty}^{\infty} R_X(t_1 - t_2 - u)h(-u) du$

$$= \int_{-\infty}^{\infty} R_X(\tau - u)h(-u) du$$

$$= R_X(\tau) * h(-\tau) \equiv R_{XY}(\tau)$$

Auto-correlation

$$E[Y(t_1)Y(t_2)] = E[Y(t_1)Y(t_2)]$$

$$= E\left[\left(\int_{-\infty}^{\infty} X(s)h(t_1 - s) ds\right)Y(t_2)\right]$$

$$= \int_{-\infty}^{\infty} R_{XY}(s - t_2)h(t_1 - s) ds$$

$$= \int_{-\infty}^{\infty} R_{XY}(u)h(t_1 - t_2 - u) du$$

$$= R_{XY}(\tau) * h(\tau)$$

$$= R_{Y}(\tau) * h(\tau) = R_{Y}(\tau)$$

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Power Spectral Density of Stationary Process

- Power spectral density
 - A function that determines the distribution of the power of the random process at different frequencies

Theorem

For a stationary random process X(t), the power spectral density is the Fourier transform of the autocorrelation function, i.e.,

$$S_X(f) = \mathcal{F}[R_X(\tau)]$$

Since $R_X(\tau) = R_X(-\tau)$, we can show $S_X(f) = S_X^*(f)$, that is, $S_X(f)$ is a real function.

Example

Consider a random process

$$X(t) = A\cos(2\pi f_0 t + \Theta), \quad \text{where } \Theta \sim \mathcal{U}[0, 2\pi]$$

Autocorrelation function

$$R_X(\tau) = \frac{A^2}{2}\cos(2\pi f_0 \tau),$$

Power spectral density

$$S_X(f) = \frac{A^2}{4} [\delta(f - f_0) + \delta(f + f_0)]$$

Power

Power from Power Spectral Density

$$P_X = \int_{-\infty}^{\infty} S_X(f) \, df$$

Power from autocorrelation

$$R_X(\tau) = \int_{-\infty}^{\infty} S_X(f) e^{j2\pi f \tau} d\tau \qquad \Longrightarrow \qquad R_X(0) = \int_{-\infty}^{\infty} S_X(f) d\tau = P_X$$

Power in the previous example

$$P_X = \int_{-\infty}^{\infty} S_X(f) \, df = \int_{-\infty}^{\infty} \left[\frac{A^2}{4} \left[\delta(f - f_0)_+ \delta(f + f_0) \right] \right] \, df$$
$$= 2 \times \frac{A^2}{4} = \frac{A^2}{2}$$

Power Spectra in LTI System

Input-Output relation in LIT system

$$Y(t) = X(t) * h(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau) d\tau = \int_{-\infty}^{\infty} x(t-\tau)h(\tau) d\tau$$

 \blacksquare Mean of Y(t)

$$m_Y=m_X\int_{-\infty}^{\infty}h(t)\,dt \qquad \iff \qquad m_Y=m_XH(0) \qquad \qquad H(f)=\int_{-\infty}^{\infty}h(t)e^{-j2\pi ft}\,dt$$

Autocorrelation and Power spectral density

$$R_Y(\tau) = R_X(\tau) * h(\tau) * h(-\tau)$$
 \iff $S_Y(f) = S_X(f)|H(f)|^2$
 $S_Y(f)$ is a real function

Crosscorrelation and Power spectral density

$$R_{XY}(\tau) = R_X(\tau) * h(-\tau) \iff S_{XY}(f) = S_X(f)H^*(f)$$

$$S_{XY}(f) \text{ is in general, a complex function}$$

Also note that

$$R_{YX}(\tau) = R_{XY}(-\tau) \iff S_{YX}(f) = S_{XY}^*(f) = S_X(f)H(f)$$

Since $S_X(f)$ is a real function

Variance

$$\sigma^2 = E[X^2(t)] = E[X(t)X(t)] = R_X(0) = \int_{-\infty}^{\infty} S_X(f) df$$

Gaussian Processes

- Gaussian processes
 - A random process X(t) is a Gaussian process if for all n and all (t_1, t_2, \ldots, t_n) , the random variables $\{X(t_i)\}_{i=1}^n$ have a jointly Gaussian density function.

Example:

$$X(t)$$
: Zero-mean stationary Gaussian RP with $S_X(f) = 5 \prod \left(\frac{f}{1000}\right)$

Determine the PDF of the random variable X(3).

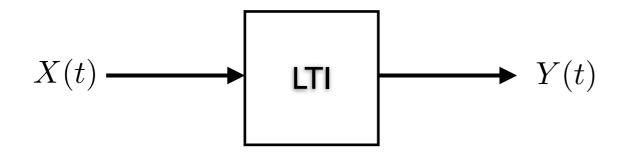
$$\sigma^2 = \int_{-\infty}^{\infty} S_X(f) \, df = 5000$$

$$f_{X(3)}(x) = \frac{1}{\sqrt{10000\pi}} e^{-\frac{x^2}{10000}}$$

Properties of Gaussian Processes

Property I

In LTI system, the input signal, X(t), which is a Gaussian random process, the output signal, Y(t) is also a Gaussian random process.

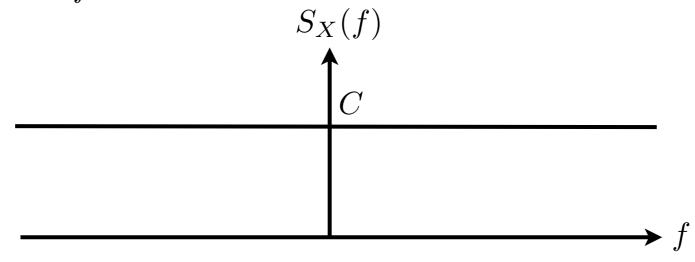


Property 2

For jointly Gaussian processes, uncorrelatedness and independence are equivalent.

White Processes

- Definition
 - A process X(t) is called a white process if it has a flat spectral density, i.e., if $S_X(f)$ is a constant for all f.



Power of white processes

$$P_X = \int_{-\infty}^{\infty} S_X(f) df = \int_{-\infty}^{\infty} C df = \infty.$$

Thermal Noise

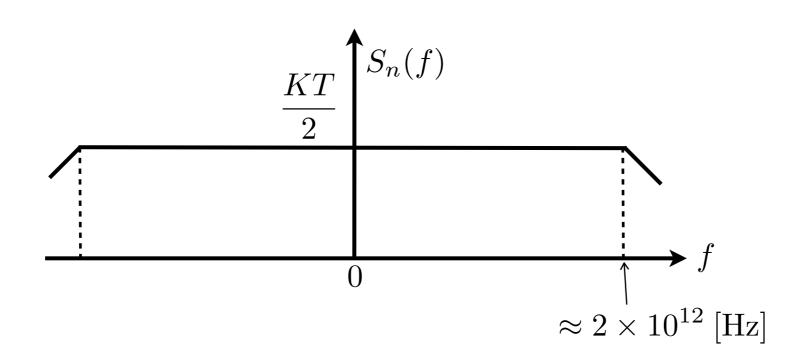
Quantum mechanical analysis of thermal noise

$$S_n(f) = \frac{hf}{2(e^{\frac{hf}{kT}} - 1)}$$

h: Planck's constant, equal to 6.6×10^{-34} J× sec

k: Boltzmann's constant, equal to 1.38×10^{-23} J/ K

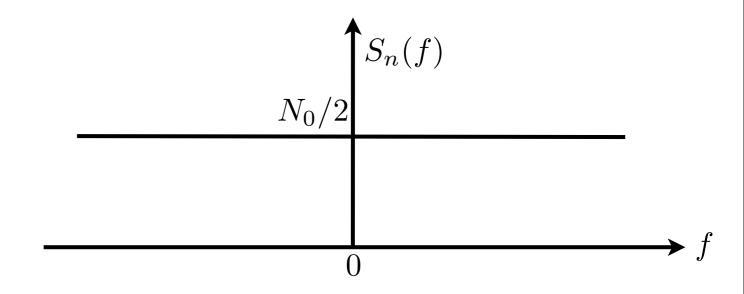
T: Temperature in Kelvin, $T=300^{\circ}$ at room temperature



Notation of White Gaussian Process

Power spectral density

$$S_n(f) = \frac{N_0}{2}$$



Autocorrelation function

$$R_n(\tau) = \mathcal{F}^{-1} \left[\frac{N_0}{2} \right] = \frac{N_0}{2} \delta(\tau)$$

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Properties of the Thermal Noise

Property I

Thermal noise is a stationary process.

Property 2

Thermal noise is a zero-mean process.

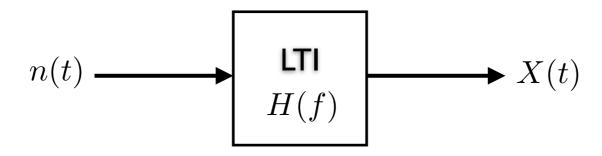
Property 3

Thermal noise is a Gaussian process.

Property 4

Thermal noise is a white process with a power spectral density $S_n(f) = \frac{kT}{2} = \frac{N_0}{2}$.

Filtered Noise Processes

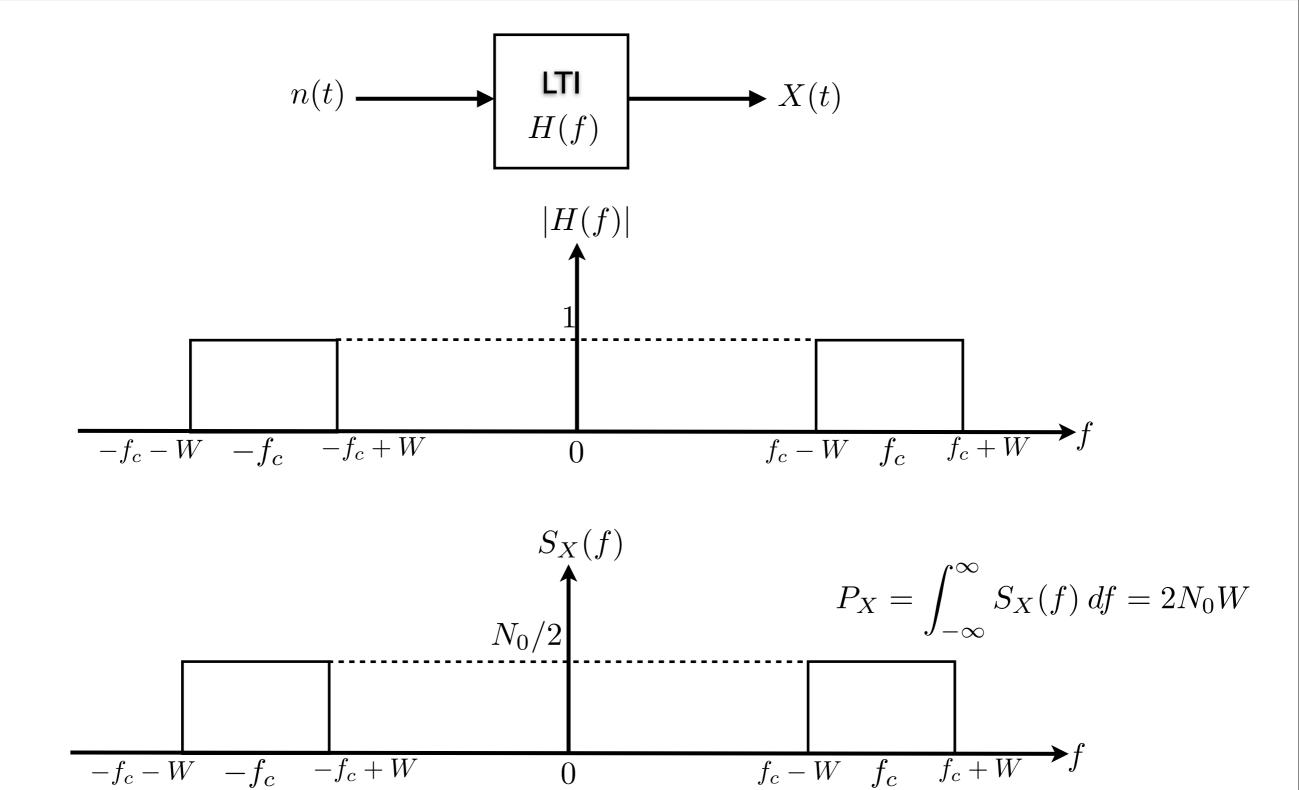


$$S_X(f) = S_n(f)|H(f)|^2 = \frac{N_0}{2}|H(f)|^2$$

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Example of Filtered White Gaussian Process



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