

KECE321 Communication Systems I

(Haykin Sec. 5.7 - Sec. 5.8)

Lecture #23, June 4, 2012

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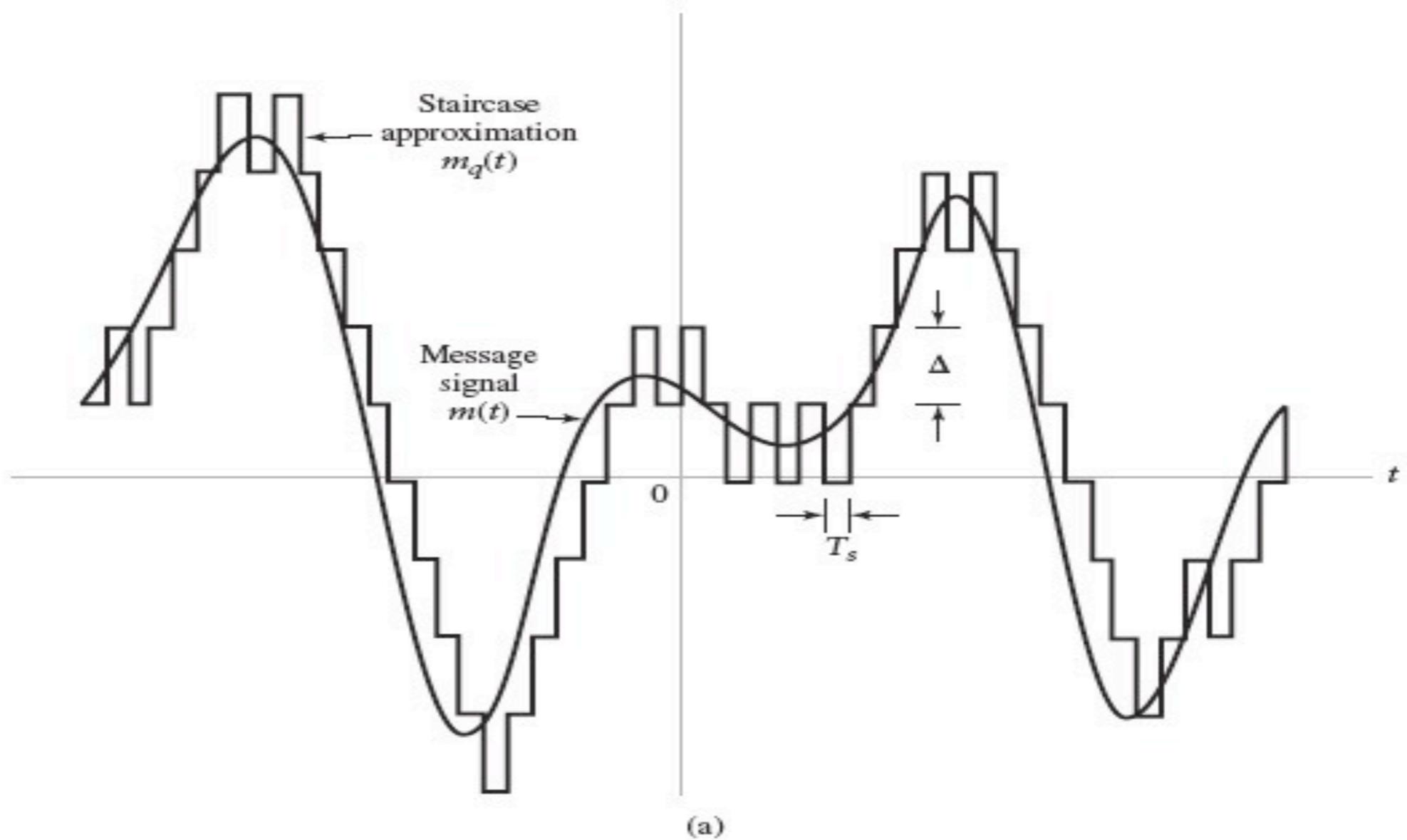
Delta Modulation

- An incoming message signal is oversampled to purposely increase the correlation between adjacent samples of the signal.
- The difference between the input signal and its approximation is quantized into only two levels - corresponding to positive and negative differences

$$e(nT_s) = m(nT_s) - m_q(nT_s - T_s)$$

$$e_q(nT_s) = \Delta \text{sgn}[e(nT_s)]$$

$$m_q(nT_s) = m_q(nT_s - T_s) + e_q(nT_s)$$



Binary sequence at modulator output 1011110100000000111111010010101111010000000110111

(b)

FIGURE 5.14 Illustration of delta modulation. (a) Analog waveform $m(t)$ and its staircase approximation $m_q(t)$. (b) Binary sequence at the modulator output.

- System details

- Comparator

- * Computes the difference between its two inputs

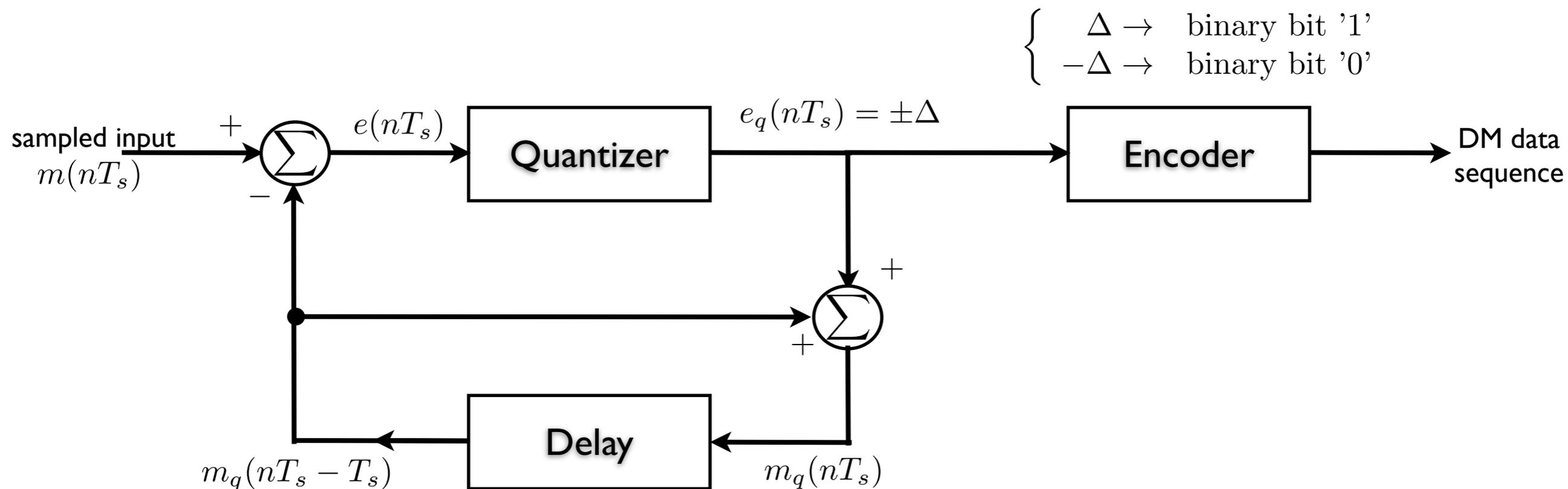
- Quantizer

- * Consider of a hard limiter with an input-output characteristic that is a scaled version of the signum function

- Accumulator

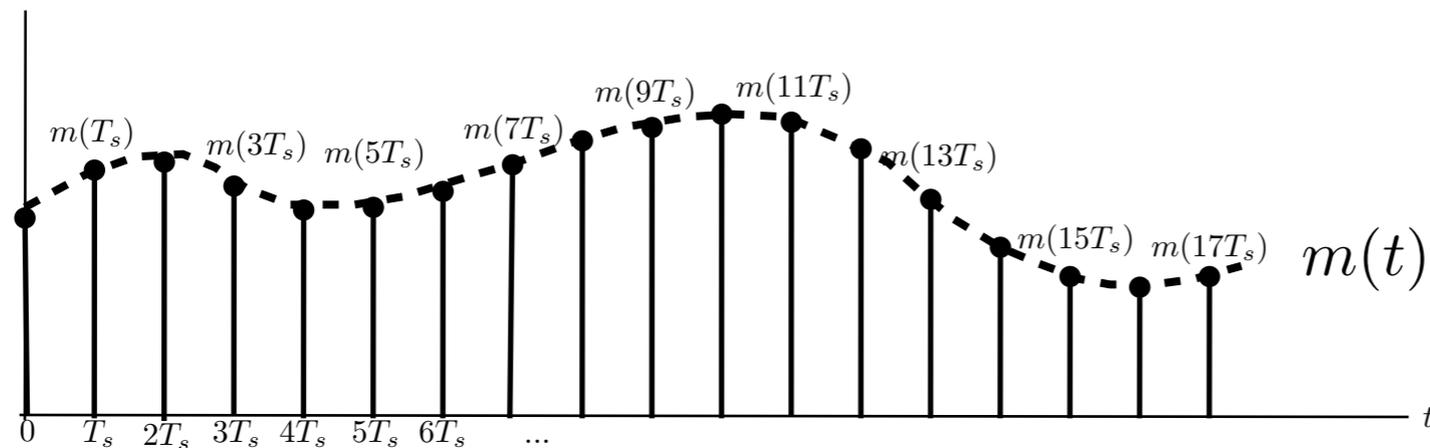
- * Operates on the quantizer output so as to produce an approximation to the message signal

$$\begin{aligned}
m_q(nT_s) &= m_q(nT_s - T_s) + e_q(nT_s) \\
&= m_q(nT_s - 2T_s) + e_q(nT_s - T_s) + e_q(nT_s) \\
&\vdots \\
&= \sum_{i=1}^n e_q(iT_s)
\end{aligned}$$



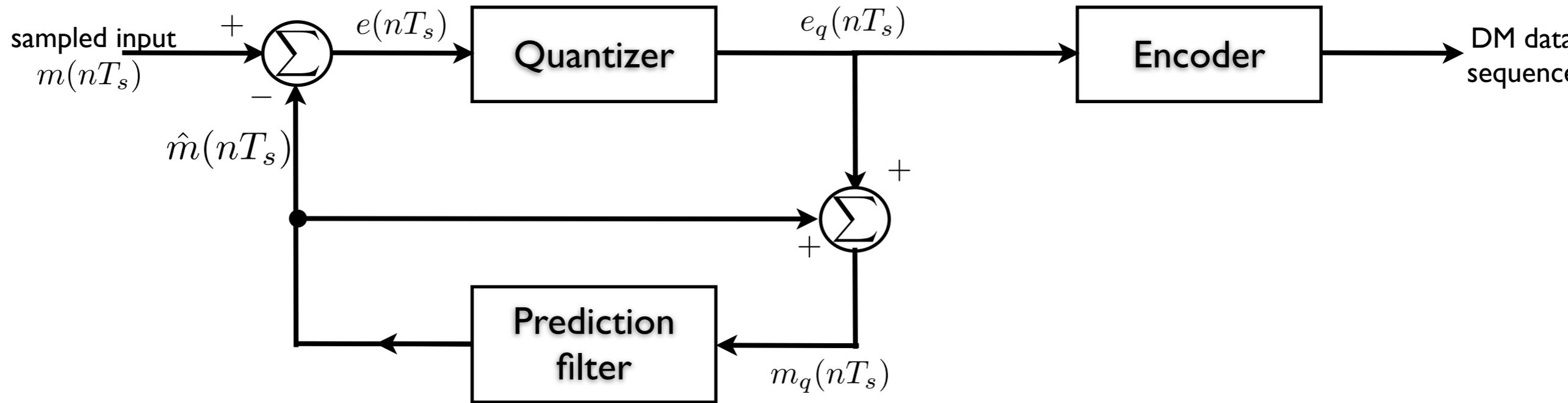
Differential Pulse-Code Modulation

- Assume the sampling rate is faster than the Nyquist rate $T_s < \frac{1}{2W}$ (or $f_s > 2W$)

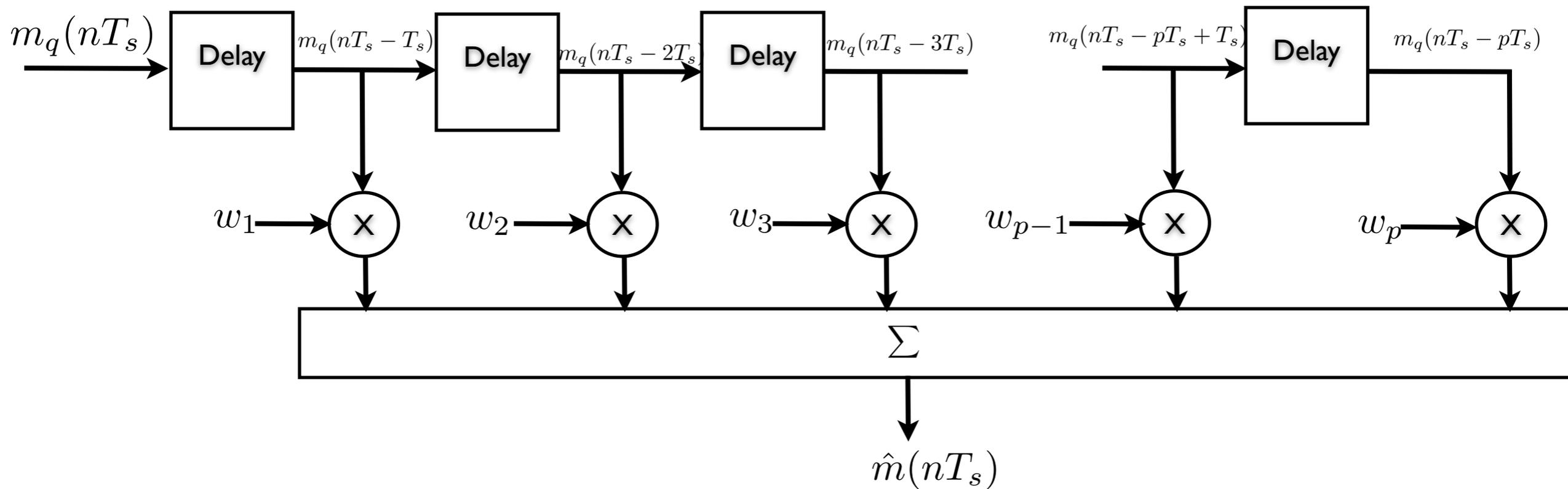


- Then sampled signals are highly correlated each other.
- Predict the future signal sample based on the previous sampled signals.
 - Differential pulse-code modulation

■ Transmitter of DPCM



• Prediction filter



- Input signal to the quantizer

$$\underbrace{e(nT_s)}_{\text{prediction error}} = m(nT_s) - \underbrace{\hat{m}(nT_s)}_{\text{predicted value}}$$

- Quantizer output

$$e_q(nT) = e(nT_s) + q(nT_s)$$

- Prediction filter input

$$\begin{aligned} m_q(nT_s) &= \hat{m}(nT_s) + e_q(nT_s) \\ &= \hat{m}(nT_s) + e(nT_s) + q(nT_s) \end{aligned}$$

$$\longrightarrow m_q(nT_s) = m(nT_s) + q(nT_s)$$

which represents a quantized version of the message sample $m(nT_s)$. That is, irrespective of the properties of the prediction filter, the quantized signal $m_q(nT_s)$ at the prediction filter input differs from the sampled message signal $m(nT_s)$ by the quantization error $q(nT_s)$.

- Accordingly, if the prediction is good, the average power of the prediction error $e(nT_s)$ will be smaller than the average power of $m(nT_s)$, so that a quantizer with a given number of levels can be adjusted to produce a quantization error with a smaller average power than would be possible if $m(nT_s)$ were quantized directly using PCM.

- Note the following:

$$E[(X_1 - X_2)^2] = E[X_1^2] + E[X_2^2] - 2E[X_1]E[X_2] \leq E[X_1^2] + E[X_2^2]$$

Receiver of DPCM

