

Communication Systems II

[KECE322_01]

<2012-2nd Semester>

Lecture #17

2012. 11. 5

School of Electrical Engineering

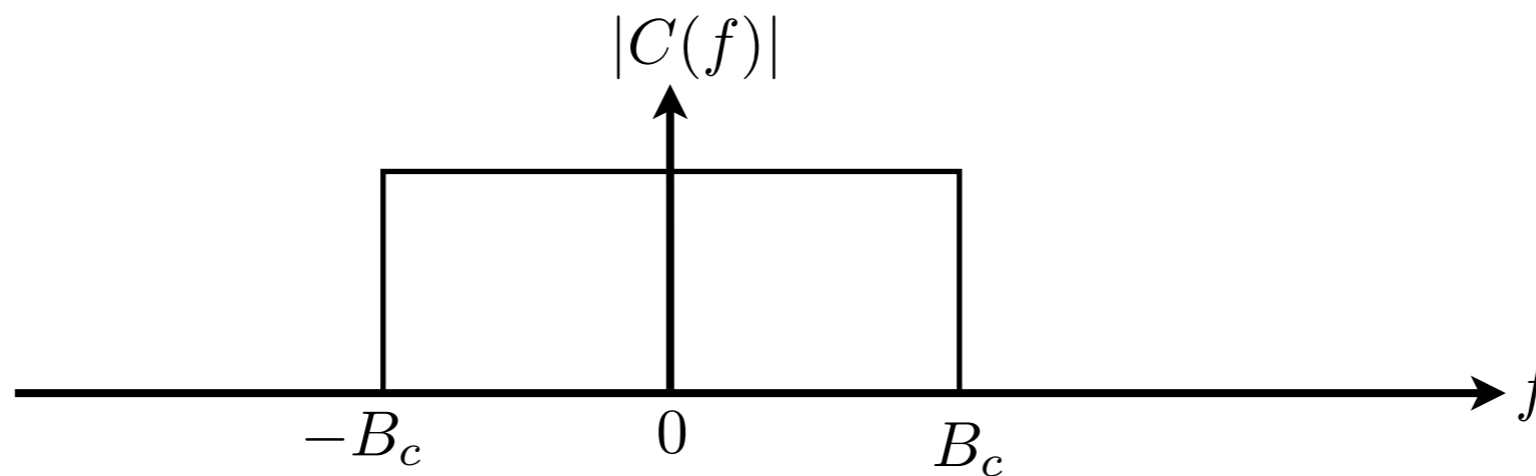
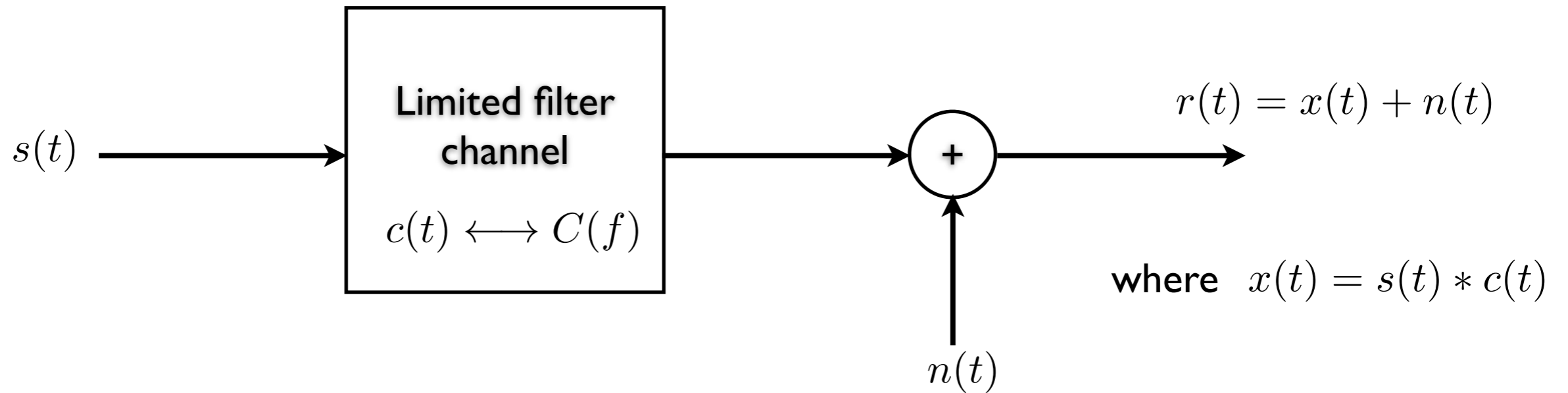
Korea University

Prof. Young-Chai Ko

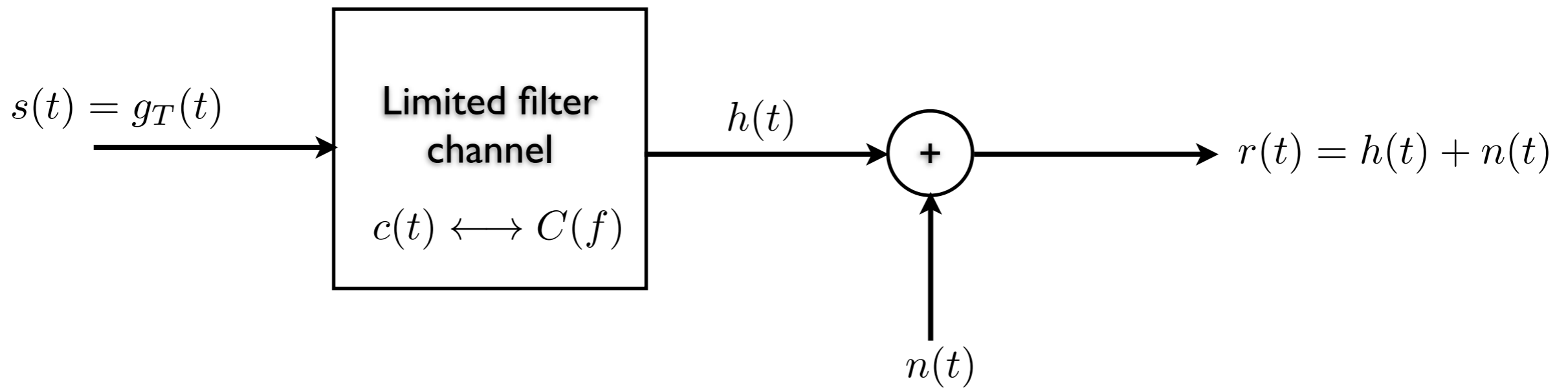
Outline

- Digital transmission through bandlimited channels
- Digital PAM transmission through bandlimited baseband channels
- Signal design for bandlimited channels

Bandlimited Channel Model



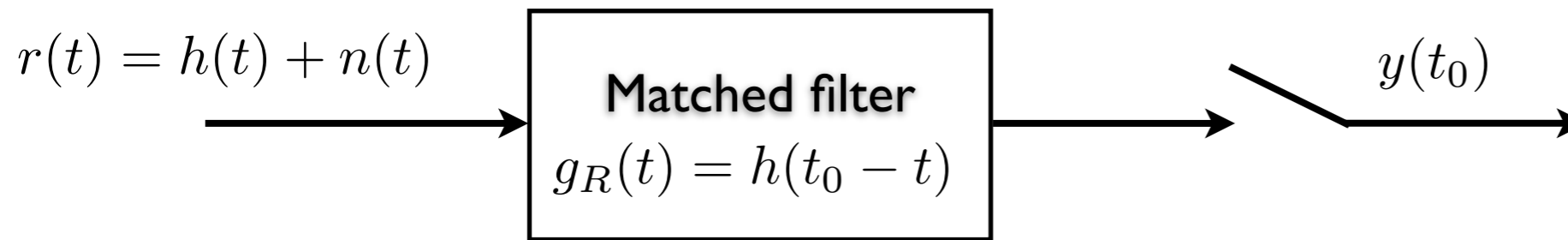
■ Suppose $s(t) = g_T(t)$



$$h(t) = \int_{-\infty}^{\infty} c(\tau)g(t - \tau) d\tau = c(t) * g_T(t)$$

$$H(f) = C(f)G_T(f)$$

■ Receiver with matched filter



t_0 : T and time delay synchronized sampling time

Frequency response of the matched filter

$$G_R(f) = \mathcal{F}[g_R(t)] = \mathcal{F}[h(t_0 - t)] = H^*(f)e^{-j2\pi ft_0}$$

Signal component at the output of the matched filter

$$y_s(t_0) = \int_{-\infty}^{\infty} |H(f)|^2 df = \mathcal{E}_h$$

Noise component at the output of the matched filter is a zero mean and a power spectral density

$$S_n(f) = \frac{N_0}{2} |H(f)|^2$$

Noise power at the output of the matched filter has a variance

$$\sigma_n^2 = \int_{-\infty}^{\infty} S_n(f) df = \frac{N_0}{2} \int_{-\infty}^{\infty} |H(f)|^2 df = \frac{N_0 \mathcal{E}_h}{2}$$

SSR at the output of the matched filter

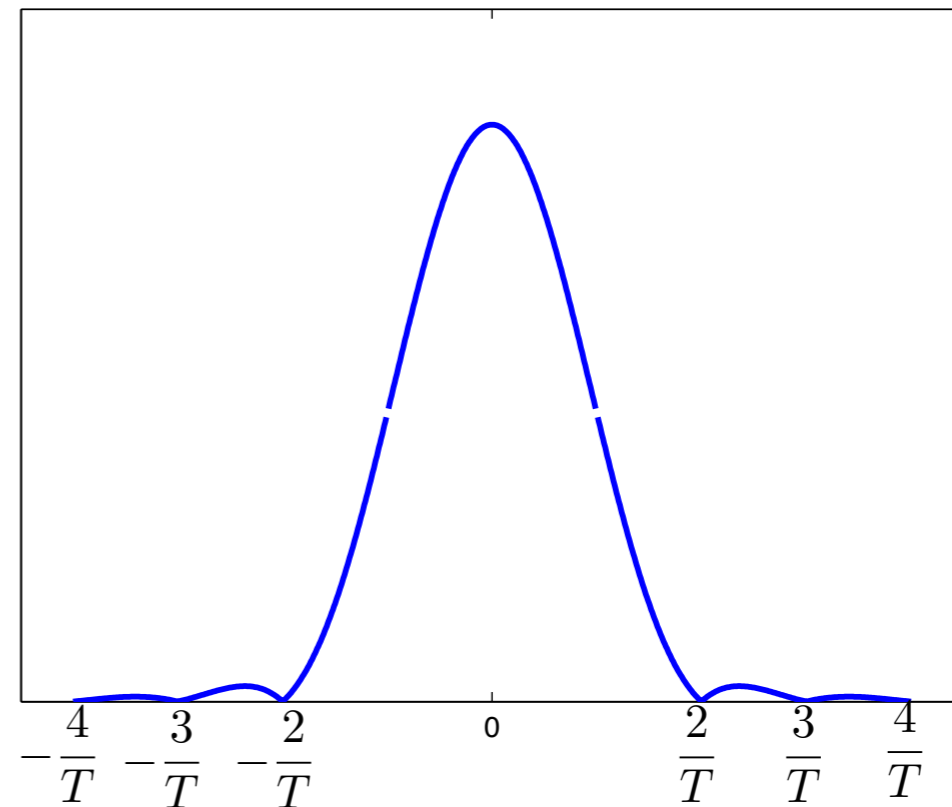
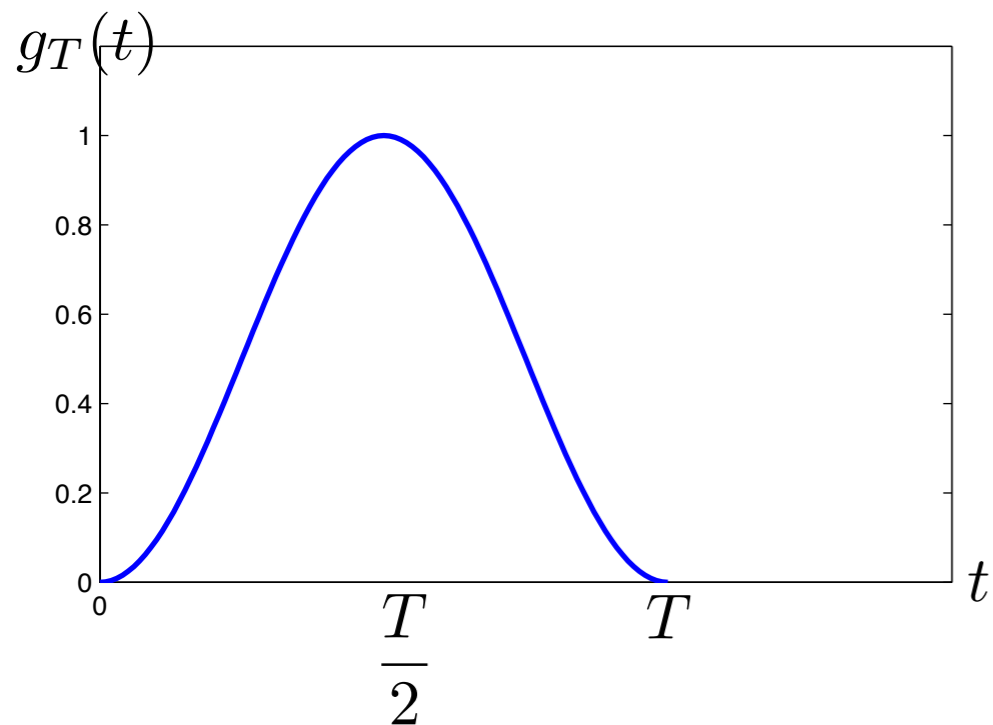
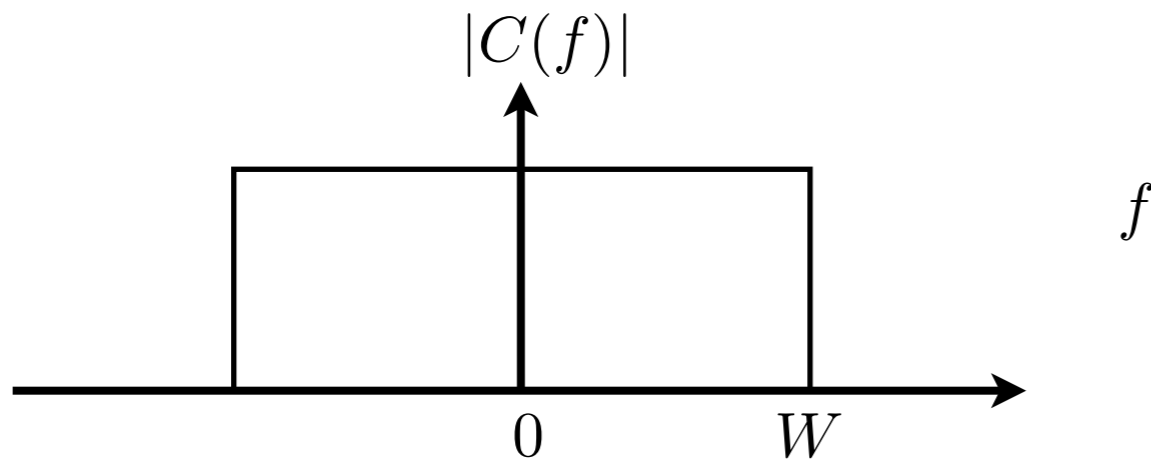
$$\left(\frac{S}{N}\right)_o = \frac{\mathcal{E}_h^2}{N_0 \mathcal{E}_h / 2} = \frac{2\mathcal{E}_h}{N_0}$$

Note that for the implementation of the matched filter at the receiver, the channel impulse response $c(t)$ must be known to the receiver.

■ Example

$$g_T(t) = \frac{1}{2} \left[1 + \cos \frac{2\pi}{T} \left(t - \frac{T}{2} \right) \right], \quad 0 \leq t \leq T$$

$$G_T(f) = \frac{T}{2} \frac{\sin \pi f T}{\pi f T (1 - f^2 T^2)} e^{-j2\pi f T} = \frac{T}{2} \frac{\text{sinc} \pi f T}{(1 - f^2 T^2)} e^{-j2\pi f T}$$



$$H(f) = C(f)G_T(f) = \begin{cases} G_T(f), & |f| \leq W \\ 0, & \text{otherwise} \end{cases}$$

Signal component at the output of the matched to $H(f)$

$$\begin{aligned} \mathcal{E}_h &= \int_{-W}^W |G_T(f)|^2 df = \frac{1}{(2\pi)^2} \int_{-W}^W \frac{(\sin(\pi fT))^2}{\pi^2 f^2 T^2 (1 - f^2 T^2)^2} df \\ &= \frac{T}{(2\pi)^2} \int_{-WT}^{WT} \frac{\sin^2 \pi \alpha}{\alpha^2 (1 - \alpha^2)^2} d\alpha \end{aligned}$$

Variance of the noise component

$$\sigma_n^2 = \frac{N_0}{2} \int_{-W}^W |G_T(f)|^2 df = \frac{N_0 \mathcal{E}_h}{2}$$

- Hence, the output SNR is

$$\left(\frac{S}{N}\right)_0 = \frac{2\mathcal{E}_h}{N_0}$$

- The amount of signal energy at the output of the matched filter depends on the value of the channel bandwidth W when the signal pulse duration is fixed. The maximum value of \mathcal{E}_h is obtained as $W \rightarrow \infty$, that is,

$$\max \mathcal{E}_h = \int_{-\infty}^{\infty} |G_T(f)|^2 df = \int_0^T g_T^2(t) dt = \mathcal{E}_g$$

- To maximize the received SNR, we must make sure that the spectrum of the transmitted signal waveform $g_T(t)$ is limited to the bandwidth of the channel.
- The impact of the channel bandwidth limitation is felt when we consider the transmission of a sequence of signal waveforms.

PAM Transmission through Bandlimited Baseband Channels

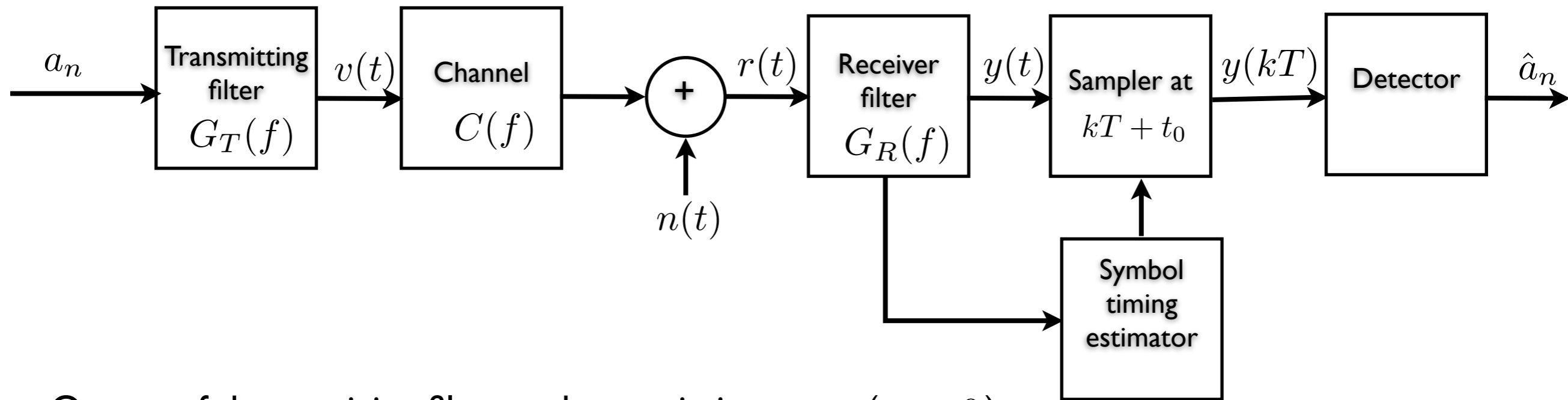
■ PAM transmit signals

$$v(t) = \sum_{n=-\infty}^{\infty} a_n g_T(t - nT),$$

where $T = \frac{k}{R_b}$ is the symbol interval, R_b is the bit rate and $\{a_n\}$ is a sequence of the amplitude levels corresponding to the sequence of k-bit blocks of information bits.

■ Received signals

$$r(t) = \sum_{n=-\infty}^{\infty} a_n h(t - nT) + n(t)$$



Output of the receiving filter under no timing error ($t_0 = 0$):

$$y(t) = \sum_{n=-\infty}^{\infty} a_n x(t - nT) + w(t)$$

where $x(t) = h(t) * g_R(t) = g_T(t) * c(t) * g_R(t)$

Sampled signal

$$y(mT) = \sum_{n=-\infty}^{\infty} a_n x(mT - nT) + w(mT)$$

or equivalently,

$$y_m = \sum_{n=-\infty}^{\infty} a_n x_{m-n} + w_m = x_0 a_m + \sum_{n \neq m} a_n x_{m-n} + w_m$$

$$y_m = x_0 a_m + \sum_{n \neq m} a_n x_{m-n} + w_m$$

↓
↓
 desired symbol Inter-Symbol interference (ISI)

Note that

$$x(t) = h(t) * g_R(t)$$

if the receiving filter $g_R(t)$ is matched to $h(t)$, then

$$\begin{aligned}
 x(0) \triangleq x_0 &= \int_{-\infty}^{\infty} h(\lambda)h(\lambda) d\lambda \\
 &= \int_{-\infty}^{\infty} h^2(t) dt \\
 &= \int_{-\infty}^{\infty} |H(f)|^2 df = \int_{-W}^W |G_T(f)|^2 |C(f)|^2 df = \mathcal{E}_h
 \end{aligned}$$

Signal Design for Bandlimited Channels

■ ISI signal

$$y_m = x_0 a_m + \sum_{n \neq m} a_n x_{m-n} + w_m$$

■ Bandlimited channel model

$$C(f) = \begin{cases} C_0 e^{-j2\pi f t_0}, & |f| \leq W \\ 0, & |f| > W \end{cases}$$

■ Output of the receiving filter

$$X(f) = G_T(f)C(f)G_R(f) = G_T(f)C(f)C_0 e^{-j2\pi f t_0}$$

- Assuming $C_0 = 1$ and $t_0 = 0$

$$X(f) = G_T(f)C(f), \quad |f| \leq W$$

■ Zero ISI condition

$$x(nT) = \begin{cases} 1, & n = 0 \\ 0, & n \neq 0 \end{cases}$$

- which is called *Nyquist condition* for zero ISI.

■ Nyquist condition for zero ISI

- A necessary and sufficient condition for $x(t)$ to satisfy

$$x(nT) = \begin{cases} 1, & n = 0 \\ 0, & n \neq 0 \end{cases}$$

is that its Fourier transform $X(f)$ must satisfy

$$\sum_{m=-\infty}^{\infty} X\left(f + \frac{m}{T}\right) = T.$$

■ Proof

$$x(t) = \int_{-\infty}^{\infty} X(f) e^{j2\pi ft} df.$$

At the sampling instants $t = nT$, it becomes

$$\begin{aligned} x(nT) &= \int_{-\infty}^{\infty} X(f) e^{j2\pi fnT} df \\ &= \sum_{m=-\infty}^{\infty} \int_{-(2m-1)/2T}^{(2m+1)/2T} X(f) e^{j2\pi fnT} df \\ &= \sum_{m=-\infty}^{\infty} \int_{-1/2T}^{1/2T} X\left(f + \frac{m}{T}\right) e^{j2\pi fnT} df \\ &= \int_{-1/2T}^{1/2T} \left[\sum_{m=-\infty}^{\infty} X\left(f + \frac{m}{T}\right) \right] e^{j2\pi fnT} df \\ &= \int_{-1/2T}^{1/2T} Z(f) e^{j2\pi fnT} df, \end{aligned}$$

where $Z(f) = \sum_{m=-\infty}^{\infty} X\left(f + \frac{m}{T}\right)$

$$Z(f) = \sum_{m=-\infty}^{\infty} X\left(f + \frac{m}{T}\right) \quad x(nT) = \int_{-1/2T}^{1/2T} Z(f) e^{j2\pi f n T} df,$$

- ◆ $Z(f)$ is periodic function with period $\frac{1}{T}$; therefore it can be expanded in terms of its Fourier series coefficients $\{z_n\}$ as

$$Z(f) = \sum_{n=-\infty}^{\infty} z_n e^{j2\pi n f T}$$

where

$$z_n = T \int_{-\frac{1}{2T}}^{\frac{1}{2T}} Z(f) e^{-j2\pi n f T} df.$$

Compare the following two:

$$z_n = T \int_{-\frac{1}{2T}}^{\frac{1}{2T}} Z(f) e^{-j2\pi n f T} df, \quad \text{and} \quad x(nT) = \int_{-1/2T}^{1/2T} Z(f) e^{j2\pi f n T} df,$$

Then we have: $z_n = T x(-nT)$

◆ Zero ISI condition

$$z_n = \begin{cases} T, & n = 0 \\ 0, & n \neq 0 \end{cases}$$

since $z_n = Tx(-nT)$ and zero ISI condition is $x(nT) = \begin{cases} 1, & n = 0 \\ 0, & n \neq 0 \end{cases}$.

▶ which yields

$$Z(f) = T,$$

or equivalently