## Data Structures and Algorithms

- Algorithm Design Techniques -

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## Algorithm Design

- So far, we focused on the efficient implementation of algorithms
- Actual data structures ignored
- The programmer is in charge
- Shift to the design of algorithms
- Five common types of algorithms to solve problems
- At least one of them works for many problems


## Algorithm Design Types

1. Greedy Algorithms
2. Divide and Conquer
3. Dynamic Programming
4. Randomized Algorithms
5. Backtracking Algorithms

## Greedy Algorithms

- Work in phases.
- In each phase, a decision is made that appears to be good, ignoring future consequences
- Take local optimum now, hoping that it is equal to the global optimum.
- If this is the case, the algorithm is correct
- Otherwise, it produced a suboptimal solution
- Simple greedy algorithms for approximate answers.
- More complicated algorithms for exact answer


## Greedy Algorithms: Examples

- Dijkstra's, Prim's, and Kruskal's algorithms
- Coin-changing problem
- To make change in U.S. currency, repeatedly dispense the largest denomination
(Ex) 17.61 dollars
one ten-dollar bill
one five-dollar bill
two one-dollar bills
two quarters, one dime, one penny
$\rightarrow$ minimize the number of bills and coins


## A Simple Scheduling Problem

## Input:

- Jobs $\boldsymbol{j}_{1}, \boldsymbol{j}_{2}, \cdots, \boldsymbol{j}_{\mathrm{N}}$, all with known running times $t_{1}, t_{2}, \cdots, t_{N}$, respectively.
- A single processor


## Goal:

- A best schedule to minimize the average completion time of jobs
- Assuming non-preemptive scheduling


## Example: Four jobs

Figure 10.2 Schedule \#1

| Job | Time |
| :--- | ---: |
| $j_{1}$ | 15 |
| $j_{2}$ | 8 |
| $j_{3}$ | 3 |
| $j_{4}$ | 10 |



Average completion time

$$
\begin{aligned}
& =(15+23+26+36) / 4 \\
& =100 / 4 \\
& =25
\end{aligned}
$$

## Example: Four jobs

Figure 10.3 Schedule \#2 (optimal)

| Job | Time |
| :--- | ---: |
| $j_{1}$ | 15 |
| $j_{2}$ | 8 |
| $j_{3}$ | 3 |
| $j_{4}$ | 10 |


| $j_{3}$ | $j_{2}$ | $j_{4}$ | $j_{1}$ |
| :--- | :--- | :--- | :--- |
| 0 | 3 | 11 | 21 |

Average completion time
$=(3+11+21+36) / 4$
$=71 / 4$
$=17.75$

## Example: Four jobs

- The second one is arranged by shortest job first, which always yields an optimal schedule.
- Generally, the total cost C of the schedule is defined by the following equation:

$$
\begin{aligned}
& \mathrm{C}=\sum_{k=1}^{n}(N-k+1) t_{i_{k}} \\
& \mathrm{C}=(N+1) \sum_{k=1}^{n} t_{i_{k}}-\sum_{k=1}^{n} k * t_{i_{k}}
\end{aligned}
$$

- The first sum is independent of the job ordering.
- The second sum affects the total cost.


## The Multiprocessor Case

## Input:

- Jobs $\boldsymbol{j}_{1}, \boldsymbol{j}_{2}, \cdots, \boldsymbol{j}_{\mathrm{N}}$, all with known running times $t_{1}, t_{2}, \cdots, t_{\mathrm{N}}$, respectively.
- A number P of processors


## Goal:

- A best schedule to minimize the average completion time of jobs
- Assuming non-preemptive scheduling


## Example



## Example

| Job | Time |
| :--- | ---: |
| $j_{1}$ | 3 |
| $j_{2}$ | 5 |
| $j_{3}$ | 6 |
| $j_{4}$ | 10 |
| $j_{5}$ | 11 |
| $j_{6}$ | 14 |
| $j_{7}$ | 15 |
| $j_{8}$ | 18 |
| $j_{9}$ | 20 |

Fig 10.6 A second optimal solution


Mean completion time

$$
\begin{aligned}
& =(3+5+6+14+15+20+30+34+38) / 9 \\
& =165 / 9=18.33
\end{aligned}
$$

## Final completion time

- What if we are only interested in when the last job finishes: final completion time
- In the previous two schedules, these completion times are 40 and 38.
- In the next schedule,
the final completion time is 34 . However,
its total completion time is 168.
- Generally, total completion time and final completion time do not go together.


## Final completion time

| Job | Time |
| :--- | ---: |
| $j_{1}$ | 3 |
| $j_{2}$ | 5 |
| $j_{3}$ | 6 |
| $j_{4}$ | 10 |
| $j_{5}$ | 11 |
| $j_{6}$ | 14 |
| $j_{7}$ | 15 |
| $j_{8}$ | 18 |
| $j_{9}$ | 20 |

Fig 10.7 Minimizing final completion time

| ${ }^{j}$ | $j_{5}$ |  | 8 | P1 |
| :---: | :---: | :---: | :---: | :---: |
| ${ }^{6}$ |  |  |  | P2 |
| $j_{1}$ | $j_{3}$ | $j_{4}$ | ${ }_{7}$ | P3 |

Mean completion time

$$
=168 / 9=18.66
$$

## Huffman Codes

- Known as file compression
- The normal ASCII character set consists of roughly 100 printable characters
- 7 bits are required to distinguish them.
- An eighth bit is added as a parity check.
- If the size of the character set is $C$, then $|\log C|$ bits are needed in a standard encoding


## Example

- Suppose that a file contains only $a, e, i, s, t$, blanks and newlines with the following frequency:

| Character | Code | Frequency | Total Bits |
| :---: | :---: | :---: | :---: |
| $a$ | 000 | 10 | 30 |
| $e$ | 001 | 15 | 45 |
| $i$ | 010 | 12 | 36 |
| $s$ | 011 | 3 | 9 |
| $t$ | 100 | 4 | 12 |
| space | 101 | 13 | 39 |
| newline | 110 | 1 | 3 |
| Total |  | 58 | 174 |

Fig 10.8 Using a standard coding scheme

## Huffman Codes

- In real life, files can be very large.
- There is usually a big disparity between the most frequent and least frequent characters.
- Reducing the file size might be preferred in some cases such as transmitting over a slow network line.
- Can achieve $25 \%$ or more savings on typical large files
- The general strategy is to use short codes for frequently occurring characters


## Tree Representation

- The binary code for the alphabet can be represented by the binary tree.


Fig 10.9 Representation of the original code in a tree

## Tree Representation



Fig 10.10 A slightly better tree

## Observations

1. The optimal tree should be a full tree: All nodes either are leaves or have two children

- Otherwise, nodes with only one child could move up a level.

2. The characters should be placed only at the leaves: Any sequence of bits can be decoded unambiguously.

- If a character is contained in a nonleaf node, it is not possible to guarantee that the decoding will be unambiguous.


## Optimal prefix code

- Prefix code: No character code is a prefix of another character code.


Fig 10.11 Optimal prefix code

## Optimal prefix code

| Character | Code | Frequency | Total Bits |
| :---: | ---: | :---: | :---: |
| $a$ | 001 | 10 | 30 |
| $e$ | 01 | 15 | 30 |
| $i$ | 10 | 12 | 24 |
| $s$ | 00000 | 3 | 15 |
| $t$ | 0001 | 4 | 16 |
| space | 11 | 13 | 26 |
| newline | 00001 | 1 | 5 |
| Total |  | 58 | 146 |

Fig 10.12 Optimal prefix code

## Huffman Codes

- How the coding tree is constructed?
- By Huffman in 1952.
- The coding system is called as Huffman code
- Algorithm sketch: Given a forest of $C$ single node trees-one for each character. The weight of a tree is equal to the sum of the frequencies of its leaves. $\mathrm{C}-1$ times, select the two trees, $\mathrm{T}_{1}$ and $T_{2}$, of smallest weight, breaking ties arbitrarily, and form a new tree with subtrees $\mathrm{T}_{1}$ and $\mathrm{T}_{2}$


## Example (1/6)

(a)
(c)
(i)
(t) ${ }^{4}$
$(\mathrm{sp})^{13}$

(a) 10
$(\mathrm{e})^{15}$
(i) ${ }^{12}$

$(\mathrm{sp})^{13}$


## Example (2/6)



## Example (3/6)

## (e) ${ }^{15}$



## Example (4/6)



## Example (5/6)



## Example (6/6)



## Extended Binary Tree

- Augment binary tree with a special "square" node at every place there is a null link: external node
- Every binary tree with $n$ nodes has $n+1$ null links.
- Every binary tree with $n$ nodes has $n+1$ external nodes.
- External (Internal) path length $E(I)$ of a binary tree is the sum of the lengths of the paths from the root to all external (internal) nodes


## Extended Binary Tree



## Properties

- The internal and external path lengths $I$ and $E$ of a binary tree with $n$ internal nodes are related by the formula $E=I+2 n$.
- It follows that binary trees with the maximum $\boldsymbol{E}$ also have maximum $I$.
- Question: Over all binary trees with $n$ internal nodes, what is the maximum and minimum possible values for $I$ ?
- The worst case is when the tree is

$$
I=\sum_{i=0}^{n-1} i=n *(n-1) / 2
$$

## Properties

- For minimum I, put as many internal nodes as close to the root as possible.

$$
\begin{aligned}
& 0+2 * 1+4 * 2+8 * 3+\ldots \\
\rightarrow & \sum_{1}^{n}|\log k|=o(n * \log n)
\end{aligned}
$$

- One such example: Complete binary tree


## Weighted External Path Length

- From a set of $n+1$ positive weights $\mathrm{a}_{1}, \mathrm{a}_{2}, \ldots$, $\mathrm{a}_{n+1}$, each of the $n+1$ external nodes in a binary tree is associated with one of the weights.
- Weighted External Path Length

$$
\mathrm{WE}=\sum_{i}^{n+1} \mathrm{a}_{i} * \mathrm{k}_{i}
$$

where $\mathrm{k}_{j}$ is the distance from the root node to the external node with weight $\mathrm{a}_{i}$

## Example



## Application

- An optimal set of codes for messages $M_{1}, \ldots$, $M_{n+1}$ to transmit the corresponding messages.
- At the receiving end, the code will be decoded using a decode tree.
- A decode tree is a binary tree in which external nodes represent messages
- The binary bits in the codes determine the branching needed at each level of the decode tree to reach the correct external node.


## Decode tree

- Codes for messages


$$
\left.\begin{array}{l}
M_{1}: l l l \\
M_{2}:
\end{array}: 0 \begin{array}{lll}
0 & 0 & 1 \\
M_{3}: & 0 & 1 \\
M_{4}: & 1
\end{array}\right] \quad \text { Huffman codes }
$$

- The cost of decoding a code word is proportional to the number of bits in the code
- Is equal to the distance of the corresponding external node from the root node.


## Problem Formalism

- Assume $\mathrm{a}_{i}$ is the relative frequency with which message $M_{i}$ will be transmitted, then the expected decode time is

$$
\mathrm{T}=\sum_{I}^{n+1} \mathrm{a}_{i} * \mathrm{~d}_{i}
$$

where $d_{i}$ is the distance of the external node for the message $M_{i}$ from the root node

- The expected decode time is minimized by choosing code words resulting in a decode tree with minimal weighted external path length


## Algorithm

procedure HUFFMAN (L, n) \{
$/ / L$ is a list of $n$ single node binary trees
for $\mathrm{i}=1$ to $\mathrm{n}-1$ do $\{$
GETNODE(T); //create a new binary tree by
LCHILD $(T) \leftarrow$ LEAST(L); //combining the trees with RCHILD $(T) \leftarrow$ LEAST(L); //the two smallest weights WT $(T) \leftarrow$ WT(LCHILD(T)) + WT(RCHILD(T)); INSERT (L, T)
\}

## Example

$$
a_{1}=2, a_{2}=3, a_{3}=5, a_{4}=7, a_{5}=9, \text { and } a_{6}=13
$$



## Approximate Bin Packing

- Solve the bin packing problem
- Run quickly but will not necessarily produce optimal solutions
- The solutions are not too far from optimal


## Approximate Bin Packing

- Input
$N$ items of size $s_{1}, s_{2}, \cdots, s_{N}$ where $0<s_{i} \leq 1$
- Goal

Pack the items in the fewest no. of bins.

## Optimal Packing

- 7 items with sizes $0.2,0.5,0.4,0.7,0.1,0.3,0.8$


Fig 10.20 Optimal packing

## Bin Packing Algorithm

- Two versions
- On-line bin packing : each item must be placed in a bin before the next item can be processed and the decision can't be changed
- Off-line bin packing: it is not necessary to do anything until all the input has been read


## On-line Algorithms

- An on-line algorithm cannot always give an optimal solution.
- Theorem: There are inputs that force any on-line bin packing algorithm to use at least $4 / 3$ the optimal number of bins.
- Three simple algorithms that guarantee that the number of bins used is no more than twice optimal.


## Next Fit

- Probably the simplest algorithm
- When processing any item, check whether it fits in the same bin as the last item.
- If it does, it is placed there
- Otherwise, a new bin is created.


## Next fit

- 7 items with sizes $0.2,0.5,0.4,0.7,0.1,0.3,0.8$

| empty |
| :---: |
| 0.5 |
| 0.2 |
| $B_{1}$ |



Fig 10.21 Using Next fit

## Next Fit

- (Theorem10.2) Let $\boldsymbol{M}$ be the optimal number of bins required to pack a list I of items. Then next fit never uses more than $2 M$ bins. There exist sequences such that next fit uses $2 M-2$ bins.


## Example for Theorem 10.2

| 0.5 |
| :---: |
| 0.5 |
| $B_{1}$ |



Fig 10.22 Optimal packing for $0.5,2 / \mathrm{N}, 0.5,2 / \mathrm{N}, \cdots$ where N is divisible by 4

## Example for Theorem 10.2



Fig 10.23 Next fit packing for $0.5,2 / \mathrm{N}, 0.5,2 / \mathrm{N}, \cdots$

## First Fit

- To scan the bins in order and place the new item in the first bin that is large enough to hold it.
- A new bin is created only when the results of previous placements have left no other alternative.
- Processing each item by scanning down the list of bins sequentially, which would take $O\left(N^{2}\right)$


## First Fit

- Items with sizes $0.2,0.5,0.4,0.7,0.1,0.3,0.8$


Fig 10.24 Using First fit (4 bins)

## First Fit

(Theorem 10.3)
Let $\boldsymbol{M}$ be the optimal number of bins required to pack a list $I$ of items. Then first fit never uses more than $\left[17 / 10^{*} N\right.$ ] bins
(Ex) The input consists of $6 M$ items of size $1 / 7+e$, followed by $6 M$ items of size $1 / 3+e$, followed by $6 M$ items of size $\frac{1}{2}+e$. One simple packing places one item of each size in a bin and requires $6 M$ bins.

## First Fit: Worst Case

| empty |
| :---: |
| $1 / 7+\varepsilon$ |
| $1 / 7+\varepsilon$ |
| $1 / 7+\varepsilon$ |
| $1 / 7+\varepsilon$ |
| $1 / 7+\varepsilon$ |
| $1 / 7+\varepsilon$ |
| $B_{1} \rightarrow B_{M}$ |


| empty |
| :--- |
| $1 / 3+\varepsilon$ |
| $1 / 3+\varepsilon$ |
| $B_{M+1} \rightarrow B_{4 M}$ |



Fig 10.25 A case where FF uses 10M bins instead of 6M

## Best Fit

- Instead of placing a new item in the fist spot that is found, it is placed in the tightest spot among all bins.
- Even though we make a more educated choice of bins, the generic bad cases are the same
- Best fit is never more than roughly 1.7 times as bad as optimal.


## Best Fit

- Items with sizes $0.2,0.5,0.4,0.7,0.1,0.3,0.8$


Fig 10.26 Best Fit

## Off-line Algorithms

- Can view the entire item list before producing an answer.
- All the on-line algorithms have difficulty in packing the large items, especially when they occur later in the input.
- This can be solved by sorting the items and placing the largest items first.
- We can then apply first fit or best fit, yielding first fit decreasing and best fit decreasing, respectively.


## First Fit Decreasing

- Items with sizes $0.8,0.7,0.5,0.4,0.3,0.2,0.1$

- Optimal, but not true in general.


## Dynamic Programming

- A problem that can be mathematically expressed recursively can also be expressed as a recursive algorithm.
- In case a recursive algorithm is not efficient, the recursive algorithm can be rewritten as a non-recursive algorithm that systematically records the answers to the subproblems in a table.
- Dynamic programming makes use of this approach.


## Inefficient Fibonacci Algorithm

```
/**
2 * Compute Fibonacci numbers as described in Chapter 1.
*/
4 int fib( int n )
{
if( n <= 1)
return 1;
else
                                return fib( n - 1 ) + fib( n - 2 );
10 }
```


## Linear Fibonacci Algorithm

```
4 int fibonacci( int n )
{ {
6 if( n <= 1 )
        return 1;
8
9 int last = 1;
10 int nextToLast = 1;
11 int answer = 1;
12 for( int i = 2; i <= n; i++ )
13 {
    answer = last + nextToLast;
    nextToLast = last;
    last = answer;
17 }
18 return answer;
19 }
```


## Recursive algorithm

- The recursive algorithm is slow due to repeated function calls

$\mathrm{F}_{\mathrm{N}-3} 3$ times $/ \mathrm{F}_{\mathrm{N}-4} 5$ times $/ \mathrm{F}_{\mathrm{N}-5} 8$ times


## Binary Search Tree

- A binary search tree T is a binary tree; either it is empty or each node in the tree contains an identifier and:

1. all identifiers in the left subtree of $T$ are less than the identifier in the root node T ;
2. all identifiers in the right subtree of T are greater than the identifier in the root node T ;
3. the left and right subtrees of T are also binary search trees.

## Two Examples



Which one is more desirable in terms of search?

## Algorithm

procedure $\operatorname{SEARCH}(\mathrm{T}, \mathrm{X}, i)$ \{
// search binary search tree T for X
$i \leftarrow \mathrm{~T}$;
while $i \neq 0$ do $\{$
case \{
$: \mathrm{X}<\operatorname{IDENT}(i): \mathrm{k} \leftarrow \operatorname{LCHILD}(i) / /$ search left tree
:X = IDENT $(i)$ : return
$: \mathrm{X}>\operatorname{IDENT}(i): i \leftarrow \operatorname{RCHILD}(i) / /$ search right tree
\}
\}

## Optimal Binary Search Tree

- Input: a list of words, $\boldsymbol{w}_{1}, \boldsymbol{w}_{2}, \cdots, \boldsymbol{w}_{\mathrm{N}}$, and fixed probabilities $\boldsymbol{p}_{1}, \boldsymbol{p}_{2}, \cdots, \boldsymbol{p}_{\mathrm{N}}$ of their occurrence.
- Output: A binary search tree that minimizes the expected total access time or total number of comparisons required.
- Hence, the tree should minimize

$$
\mathrm{T}=\sum_{T}^{n} p_{i} *\left(1+d_{i}\right)
$$

where $d_{i}$ is the depth of word $w_{i}$ in the tree

## Sample Input

| Word | Probability |
| :--- | :---: |
| a | 0.22 |
| am | 0.18 |
| and | 0.20 |
| egg | 0.05 |
| if | 0.25 |
| the | 0.02 |
| two | 0.08 |

## Possible BST \#1

- Use a greedy approach where the word with the highest probability was placed at the root.

| $w_{i}$ | $p_{i}$ |
| :---: | :---: |
| a | 0.22 |
| am | 0.18 |
| and | 0.20 |
| egg | 0.05 |
| if | 0.25 |
| the | 0.02 |
| two | 0.08 |
| Totals | 1.00 |



## Possible BST \#1

|  | Input |  | Tree \#1 |  |
| :---: | :---: | :---: | :---: | :---: |

## Possible BST \#2

- Perfectly balanced search tree.

Input
Tree \#2

| Word | Probability | Access Cost |  |
| :---: | :---: | :---: | :---: |
| $w_{i}$ | $p_{i}$ | Once | Sequence |
| a | 0.22 | 3 | 0.66 |
| am | 0.18 | 2 | 0.36 |
| and | 0.20 | 3 | 0.60 |
| egg | 0.05 | 1 | 0.05 |
| if | 0.25 | 3 | 0.75 |
| the | 0.02 | 2 | 0.04 |
| two | 0.08 | 3 | 0.24 |
| Totals | 1.00 |  | 2.70 |

## Possible BST \#3



## Comparison

| Input |  | Tree \#1 |  | Tree \#2 |  | Tree \#3 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Word | Probability | Access Cost |  | Access Cost |  | Access Cost |  |
| $w_{i}$ | $p_{i}$ | Once | Sequence | Once | Sequence | Once | Sequence |
| a | 0.22 | 2 | 0.44 | 3 | 0.66 | 2 | 0.44 |
| am | 0.18 | 4 | 0.72 | 2 | 0.36 | 3 | 0.54 |
| and | 0.20 | 3 | 0.60 | 3 | 0.60 | 1 | 0.20 |
| egg | 0.05 | 4 | 0.20 | 1 | 0.05 | 3 | 0.15 |
| if | 0.25 | 1 | 0.25 | 3 | 0.75 | 2 | 0.50 |
| the | 0.02 | 3 | 0.06 | 2 | 0.04 | 4 | 0.08 |
| two | 0.08 | 2 | 0.16 | 3 | 0.24 | 3 | 0.24 |
| Totals | 1.00 |  | 2.43 |  | 2.70 |  | 2.20 |

## Structure of Optimal BST

- Place sorted words $w_{\text {Leff }}, w_{L e f t+1}, \cdots, w_{i}, \cdots$, $w_{\text {Right-1 }}, w_{\text {Right }}$ into a binary search tree.



## Cost Formula

$$
\begin{aligned}
& C_{\text {Left Right }}=\min _{\text {LeftSRKkth }}\left\{p_{i}+C_{L e f f, i-1}+C_{i+1, \text { Right }}\right. \\
& \left.+\sum_{j=\pi \in t i t}^{i=1} p_{j}+\sum_{j=i+1}^{R_{i j l} h t} p_{j}\right\}
\end{aligned}
$$

- For each subrange of words starting from a single word, the algorithm produces the cost and root of the optimal BST as in the following table.


## Computation for the sample input



## Computation of table entry for am..if



$$
0+0.80+0.68=1.48
$$

$$
0.18+0.35+0.68=1.21
$$


$0.56+0.25+0.68=1.49$

$0.66+0+0.68=1.34$

